

- Generalized Uncertainty Principle
- Free particle II: particle dynamics

### IV<sub>3</sub> The Free Particle at t=0:

Recap:

→ localized wave packet →  $\Psi(x, t) = \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{+\infty} \Phi(p, t) e^{i \frac{px}{\hbar}} dp$

↑  
state of definite momentum

↑  
quantum amplitude

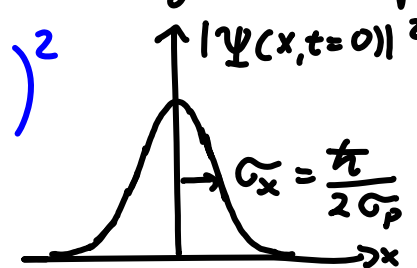
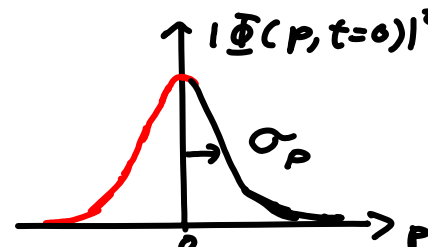
↑  
superposition

→ Example: gaussian wave packet:

$$\Phi(p, t=0) = \frac{1}{(2\pi)^{1/4} \sqrt{\sigma_p}} e^{-p^2/4\sigma_p^2}$$



$$\Psi(x, t=0) = \frac{1}{(2\pi)^{1/4} \sqrt{\frac{\hbar}{2\sigma_p}}} e^{-\frac{x^2}{4\left(\frac{\hbar}{2\sigma_p}\right)^2}}$$



$$\sigma_x \sigma_p = \frac{\hbar}{2}$$

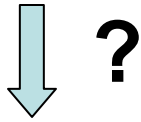
### IV<sub>4</sub> The Generalized Uncertainty Principle:

$$\sigma_A^2 \sigma_B^2 \geq \left( \frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2$$

always

where:  $[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A}$ : Commutator of  $\hat{A}$  and  $\hat{B}$

$$\sigma_A^2 \cdot \sigma_B^2 \geq \left( \frac{1}{2i} [\langle f|g \rangle - \langle g|f \rangle] \right)^2$$



$$\sigma_A^2 \sigma_B^2 \underset{\text{always}}{\geq} \left( \frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2$$

$$\langle f|g \rangle = \langle \underbrace{(\hat{A} - \langle A \rangle)}_{\text{hermitian}} \psi | (\hat{B} - \langle B \rangle) \psi \rangle$$

$$= \langle \psi | (\hat{A} - \langle A \rangle) (\hat{B} - \langle B \rangle) \psi \rangle$$

$$= \langle \psi | \hat{A} \hat{B} - \hat{A} \langle B \rangle - \langle A \rangle \hat{B} + \langle A \rangle \langle B \rangle | \psi \rangle$$

$$\begin{aligned}
\Rightarrow \underline{\langle f|g \rangle} &= \langle \psi | \hat{A} \hat{B} \psi \rangle - \langle B \rangle \langle \psi | \hat{A} \psi \rangle \\
&\quad - \langle A \rangle \langle \psi | \hat{B} \psi \rangle + \langle A \rangle \langle B \rangle \underbrace{\langle \psi | \psi \rangle}_1 \\
&= \langle \hat{A} \hat{B} \rangle - \langle B \rangle \langle A \rangle - \langle A \rangle \langle B \rangle + \langle A \rangle \langle B \rangle \\
&= \underline{\langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle B \rangle}
\end{aligned}$$

→ Similar: (simply exchange A and B):

$$\langle g|f \rangle = \langle \hat{B} \hat{A} \rangle - \langle B \rangle \langle A \rangle = \langle \hat{B} \hat{A} \rangle - \langle A \rangle \langle B \rangle$$

$$\begin{aligned}
\Rightarrow \underline{\langle f|g \rangle - \langle g|f \rangle} &= \langle \hat{A} \hat{B} \rangle - \langle \hat{B} \hat{A} \rangle \\
&= \langle [\hat{A}, \hat{B}] \rangle
\end{aligned}$$

where  $[\hat{A}, \hat{B}] = \hat{A} \hat{B} - \hat{B} \hat{A}$  : commutator of the two operators  $\hat{A}$  and  $\hat{B}$

## generalized uncertainty principle

$$\sigma_A^2 \sigma_B^2 \underset{\text{always}}{\geq} \left( \frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2$$

- ⇒ if operator  $\hat{A}$  and  $\hat{B}$  do not commute: (i.e.  $[\hat{A}, \hat{B}] \neq 0$ )
- uncertainty principle
  - incompatible observables
  - no shared complete set of eigenfunctions
  - on a single quantum system: sequence of measurements matters: different results! Measurements change state!

• Example:

suppose:  $\hat{A} = x$   
position operator

$\hat{B} = \frac{\hbar}{i} \frac{\partial}{\partial x}$   
momentum operator

$\Rightarrow$  what is  $[\hat{x}, \hat{p}] = \hat{x}\hat{p} - \hat{p}\hat{x} = ?$

$\rightarrow$  let this act on a test function  $f(x)$

(never do math with operators without a test function!)

$$\begin{aligned} \underline{[\hat{x}, \hat{p}]f(x)} &= \left[ x \frac{\hbar}{i} \frac{\partial f}{\partial x} - \frac{\hbar}{i} \frac{\partial}{\partial x} (x f(x)) \right] \\ &= \frac{\hbar}{i} \left[ x \frac{\partial f}{\partial x} - x \frac{\partial f}{\partial x} - f(x) \right] = \underline{i\hbar f(x)} \end{aligned}$$

$$\Rightarrow [\hat{x}, \hat{p}] = i\hbar \Rightarrow \underline{\langle [\hat{x}, \hat{p}] \rangle} = i\hbar \langle \underbrace{\psi | \psi} \rangle = \underline{i\hbar}$$

$$\Rightarrow \sigma_x^2 \sigma_p^2 \geq \left( \frac{1}{2i} i\hbar \right)^2 = \left( \frac{\hbar}{2} \right)^2 \Rightarrow \boxed{\sigma_x \sigma_p \geq \frac{\hbar}{2}}$$

Heisenberg's uncertainty principle!

• why inequality in  $\sigma_x \sigma_p \geq \frac{\hbar}{2}$ ?

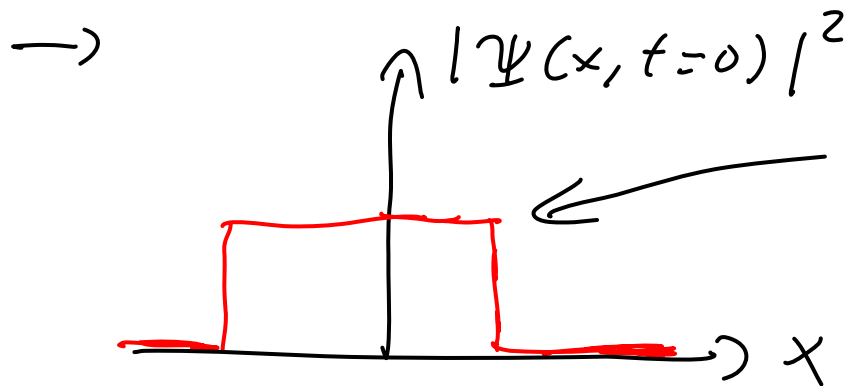
• Compare:



Gaussian wave packet  
at  $t=0$ :

$$\text{had } \sigma_x \sigma_p = \frac{\hbar}{2}$$

minimum uncertainty



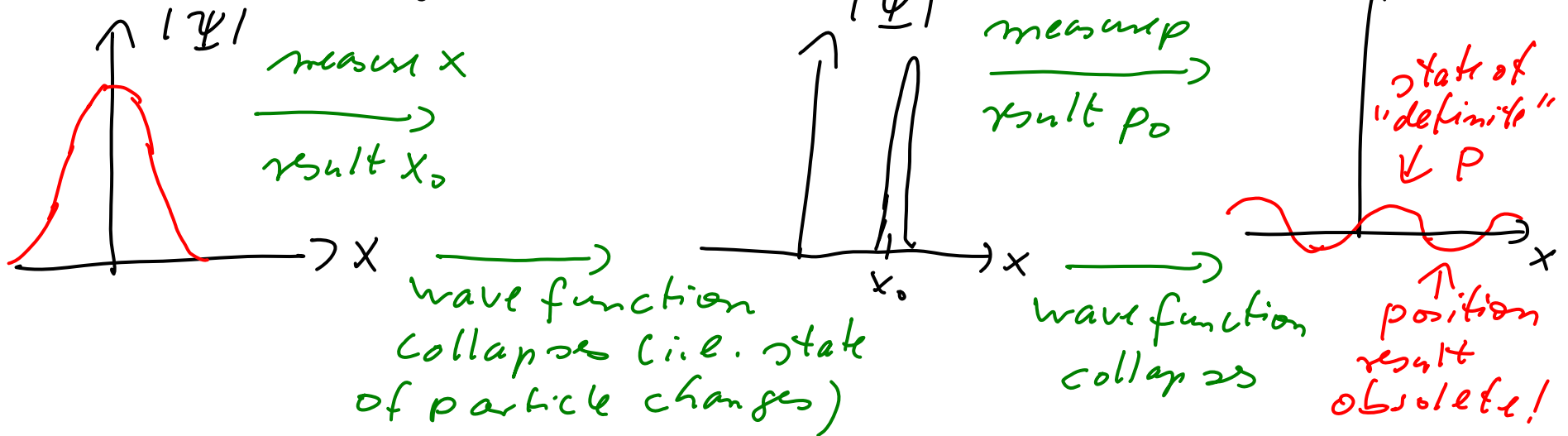
sharp corner!  
=> will need lot's of  
Fourier components  
=> large spread in  $p$  to  
get  $\Psi(x, t=0)$

$$\Rightarrow \sigma_x \sigma_p \gg \frac{\hbar}{2} \text{ here}$$

• What does the Heisenberg Uncertainty Principle mean?

- (On sequence of the statistical interpretation in quantum mechanics)
- need to consider large number of identically prepared quantum systems / particles!
- > measure  $x$  on half and momentum  $p$  on other half => Calculate  $\sigma_x, \sigma_p$  from results
- => will always find  $\sigma_x \sigma_p \geq \hbar/2$

- for a single particle:





• some numbers:

$$\sigma_x \sigma_p \geq \frac{\hbar}{2} \Rightarrow \sigma_x \underbrace{\sigma_v}_{\substack{\uparrow \\ \text{velocity} = p/m}} \geq \frac{\hbar}{2m} \approx \begin{cases} 0.5 \frac{\text{cm}^2}{\text{s}} \text{ for } e^- \\ 5 \cdot 10^{-27} \text{ cm}^2/\text{s} \\ \text{for } 0.1 \text{ g pea} \end{cases}$$

example: for  $\sigma_x = 0.5 \text{ \AA}$  (Bohr radius)

→ electron:  $\sigma_v \geq 10^8 \text{ cm/s}$  large!

[classical velocity in Bohr atom  $\approx 10^9 \text{ cm/s}$ ]

→ pea:

$$\sigma_v \geq 10^{-18} \text{ cm/s} \quad \text{small!}$$

⇒ Heisenberg's uncertainty principle

does not matter for macroscopic particles!

• Heisenberg uncertainty principle and ground state

Energies:

For particle in ground state confined in well of some length scale  $\sigma_x$ : 3D potential well

Kinetic energy:  $\langle KE \rangle = \frac{\langle p^2 \rangle}{2m} = \frac{\langle p_x^2 \rangle + \langle p_y^2 \rangle + \langle p_z^2 \rangle}{2m}$

for 3D and  $\rightarrow \frac{3 \sigma_{p_x}^2}{2m} \geq \frac{3}{2m} \left( \frac{\hbar}{2} \frac{1}{\sigma_x} \right)^2$   
 $\uparrow \sigma_x \sigma_{p_x} \geq \hbar/2$

$\langle p_x^2 \rangle = \langle p_y^2 \rangle = \langle p_z^2 \rangle$   
 (symmetric)

$\sigma_{p_x} = \sqrt{\langle p_x^2 \rangle - \underbrace{\langle p_x \rangle^2}_{0 \text{ here}}}$

$\Rightarrow \sigma_{p_x} = \sigma_{p_y} = \sigma_{p_z}$

Example: proton in nucleus

$m_p = 1.7 \cdot 10^{-27} \text{ kg}$      $\sigma_x \approx 10^{-14} \text{ m}$

$\Rightarrow \langle KE \rangle \approx \frac{3}{2 \cdot 1.7 \cdot 10^{-27} \text{ kg}} \left( \frac{10^{-34} \text{ J}}{2 \cdot 10^{-14} \text{ m}} \right)$

$\approx 0.1 \text{ MeV}$  ← correct order magnitude for nuclear binding energies!

## IV<sub>5</sub> The Free Particle II: Particle Dynamics:

so far: wave packet at  $t=0$ :  $\Psi(x, t=0) = \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{+\infty} \Phi(p, t=0) e^{i\frac{px}{\hbar}} dp$

$\Rightarrow$  How do they evolve in time?

$\Rightarrow$  Need to include time-dependence of the states of definite momentum and energy (for free particle!)

$\Rightarrow e^{-iE/\hbar \cdot t}$

$$\begin{aligned} \Rightarrow \Psi(x, t) &= \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{+\infty} \Phi(p) e^{i\frac{px}{\hbar}} e^{-i\frac{E(p)}{\hbar}t} dp \\ &= \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{+\infty} \Phi(p) e^{i\frac{px}{\hbar}} e^{-i\frac{p^2}{2m}\frac{t}{\hbar}} dp \quad \leftarrow E = \frac{p^2}{2m} \text{ for free particle} \\ &= \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{+\infty} \Phi(p, t) e^{i\frac{px}{\hbar}} dp \end{aligned}$$

with the momentum space wave function

$$\Phi(p, t) = \Phi(p) e^{-i p^2 / 2m t / \hbar} \text{ for the free particle}$$

Note:  $\Rightarrow |\Phi(p, t)|^2$  is time-indep. for the free particle

$$\text{free particle} \Leftrightarrow \text{no forces} \Leftrightarrow \vec{F} = \frac{d\vec{p}}{dt} \stackrel{!}{=} 0$$