

P3360 / AEP 3630

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Lecture 10

## Negative Feedback

Good amp :

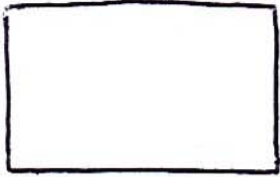
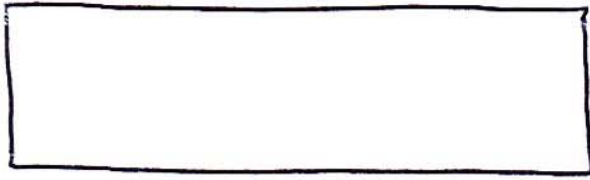
- $R_{in} \gg R_s$
- $R_{out} \ll R_L$
- $G(\omega) = \text{const}$

"Bare" op-amp problems :

- small active range
- large  $G$  variations
- $G \propto \frac{1}{\omega}$  for  $\omega_c \gg 10\text{Hz}$
- $R_{out}$  is fairly large

$$v_{out} =$$

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- throw away \_\_\_\_\_ to make  
a stable circuit, indep. of \_\_\_\_\_

Advantages of negative F.B.

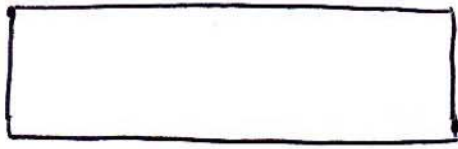
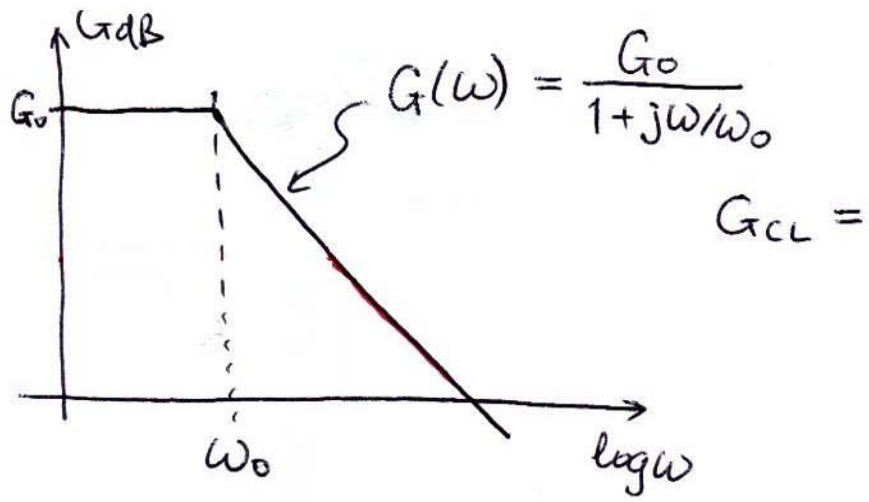
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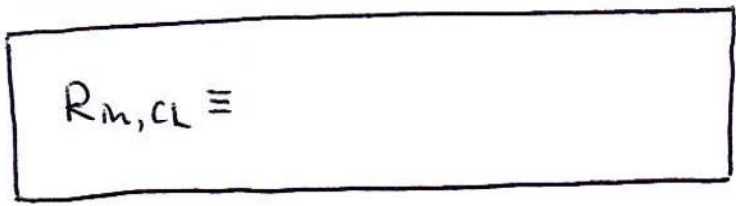
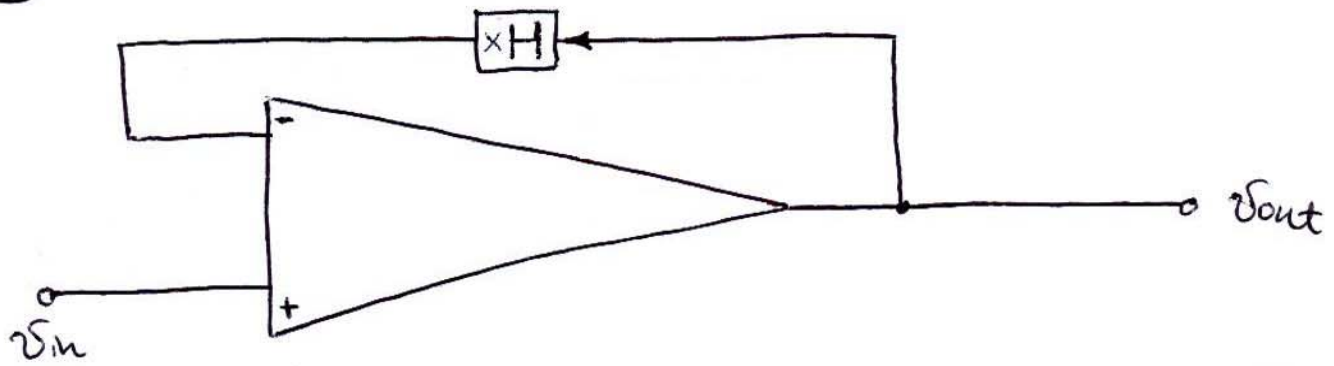
$$(v_m)_{active} =$$

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$$V_{out} =$$

$$V_{out} =$$

$$R_{out, CL} =$$

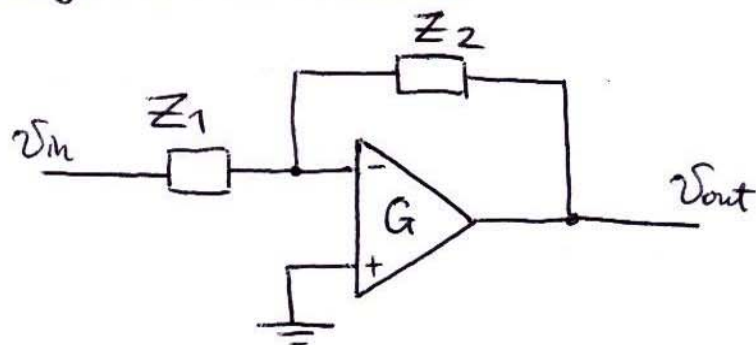
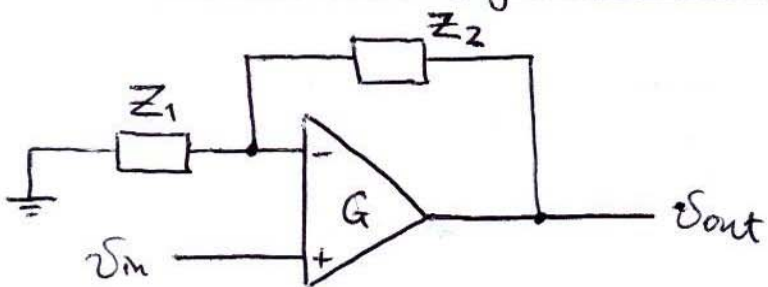
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Rules for analyzing negative F.B. circuits

- 1) current rule:
- 2) voltage rule:

Lecture 11

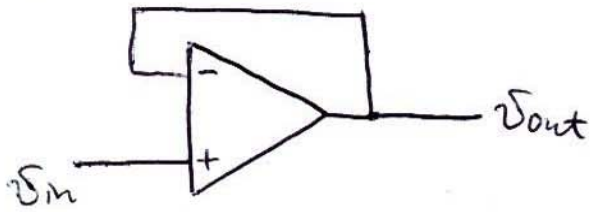
Two basic configurations with negative feedback



# Applications of neg. feedback

(2)

## ① voltage follower

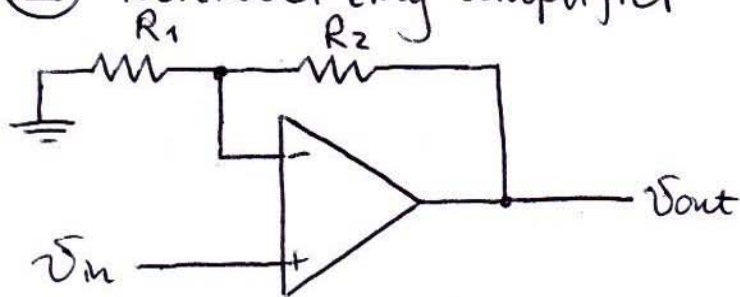


$$v_{in} \text{ --- } v_{out}$$

$$G_{CL} = \frac{G}{1+GH} \approx 1, \quad G \gg 1$$

- draws no current
- drive low  $Z$  load with high  $Z$  source

## ② noninverting amplifier



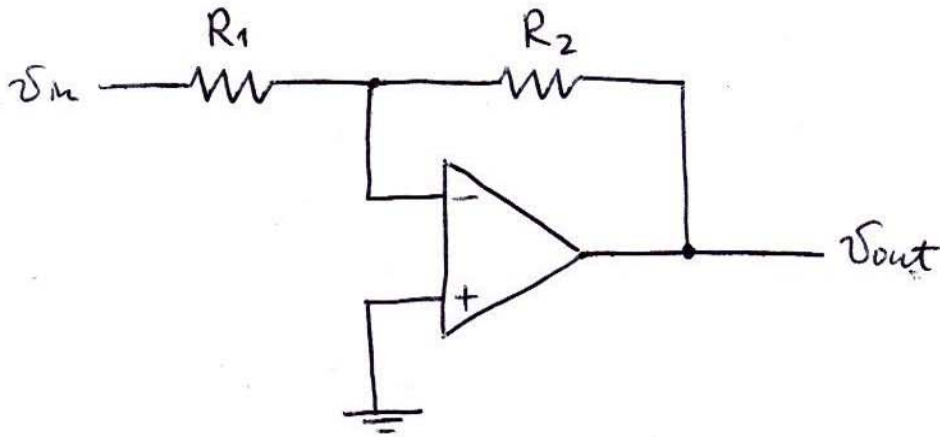
$$G_{CL} = \frac{R_1 + R_2}{R_1}$$

$$R_{in,CL} = R_{in}(1+GH)$$

$$R_{out,CL} = \frac{R_{out}}{1+GH}$$

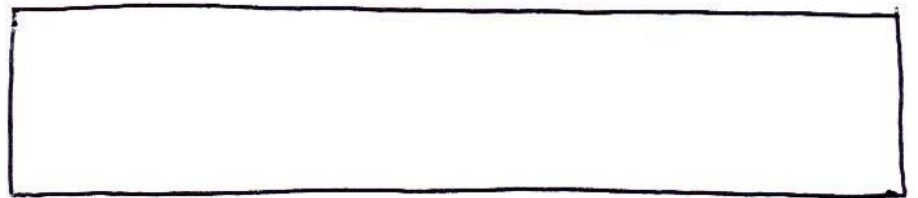
③ inverting amplifier

③



$$G_{CL} = -\frac{1}{H'} = -\frac{R_2}{R_1}$$

④ summing circuit



## Active filters

Feedback network contains  $Z(\omega)$

Pros :

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Cons :

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Q: ideal integrator & differentiator : poles & zeros of  $G(s)$ ?

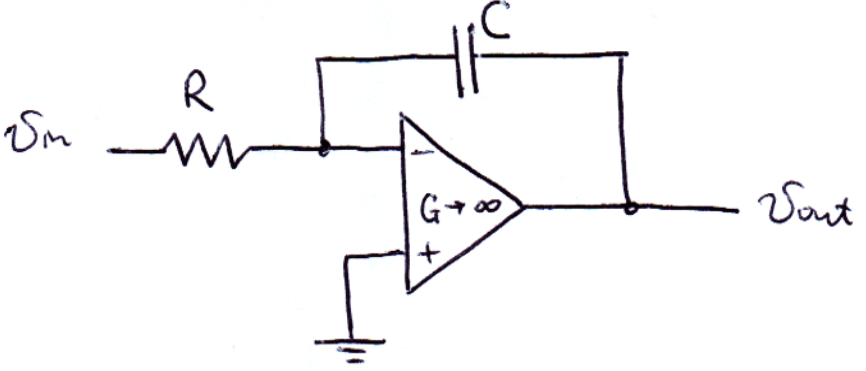


# P3360/AEP3630

## Lecture 12

### Integrator

$$v_{out} \propto \int v_{in} dt, \Rightarrow G_{cl}(s) \propto$$

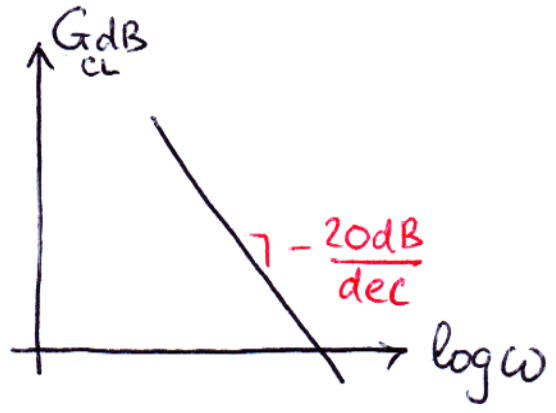
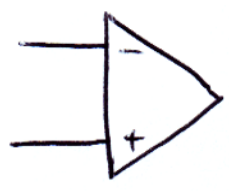


AC response :

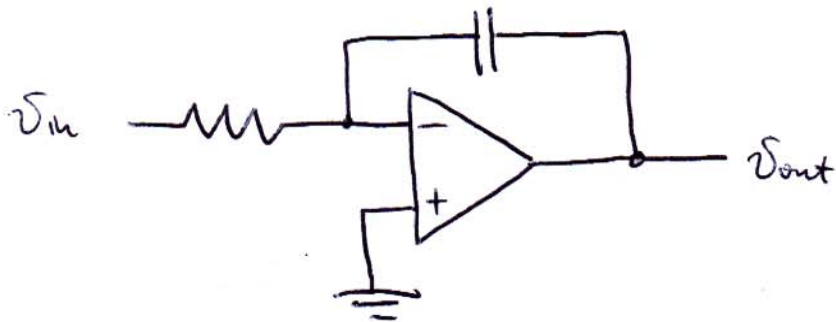
$$G_{cl}(\omega) =$$

Problem 1 :

Problem 2 :

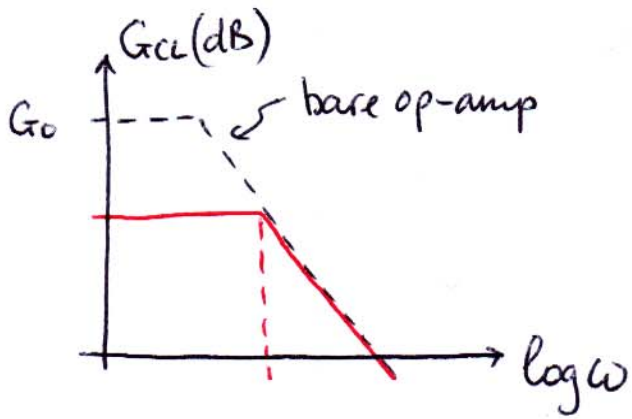


## Leaky integrator



$$G_{CL}(\omega) \approx$$

$$G_{CL}(\omega) =$$

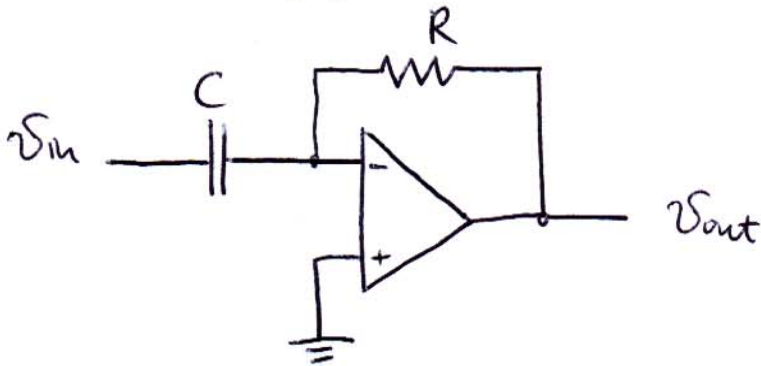


Pros:

Cons:

## Differentiator

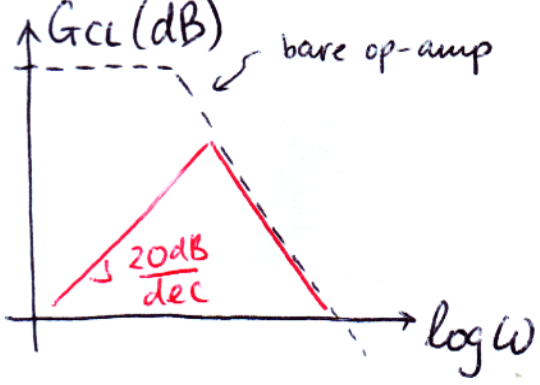
$$v_{out} \propto \frac{d}{dt} v_{in} \quad , \Rightarrow \quad G_{CL}(s) \propto$$



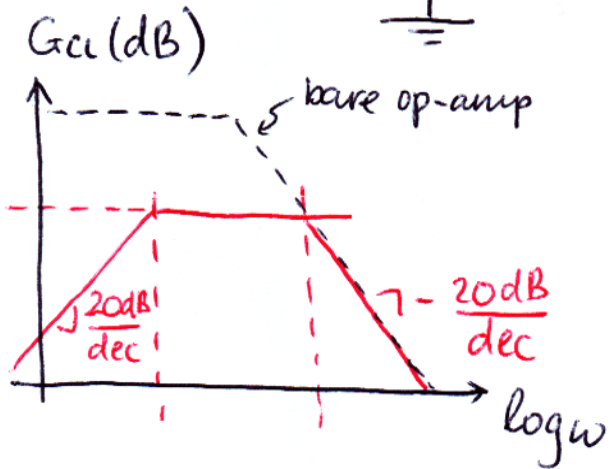
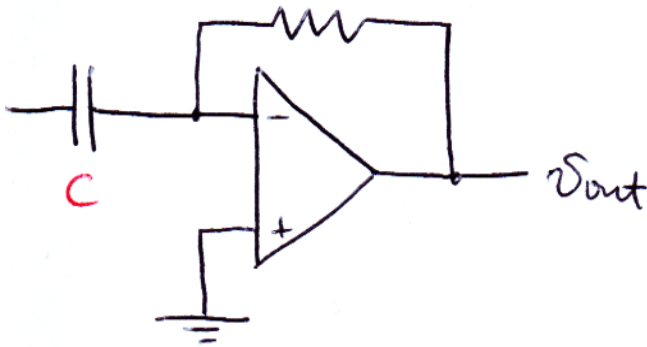
AC response:

$$G_{CL}(\omega) =$$

Problem :



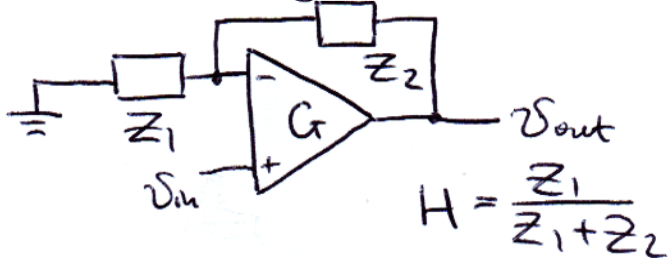
Soln :



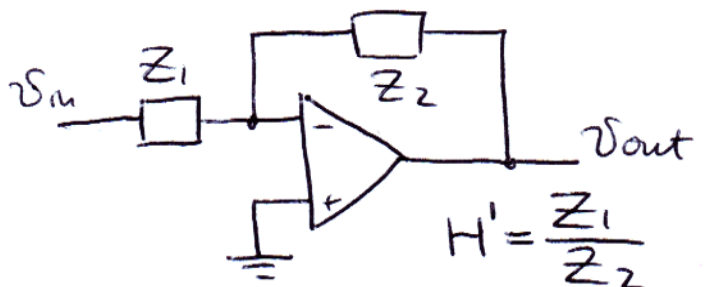
Pros:

Cons:

Stability



$$H = \frac{Z_1}{Z_1 + Z_2}$$

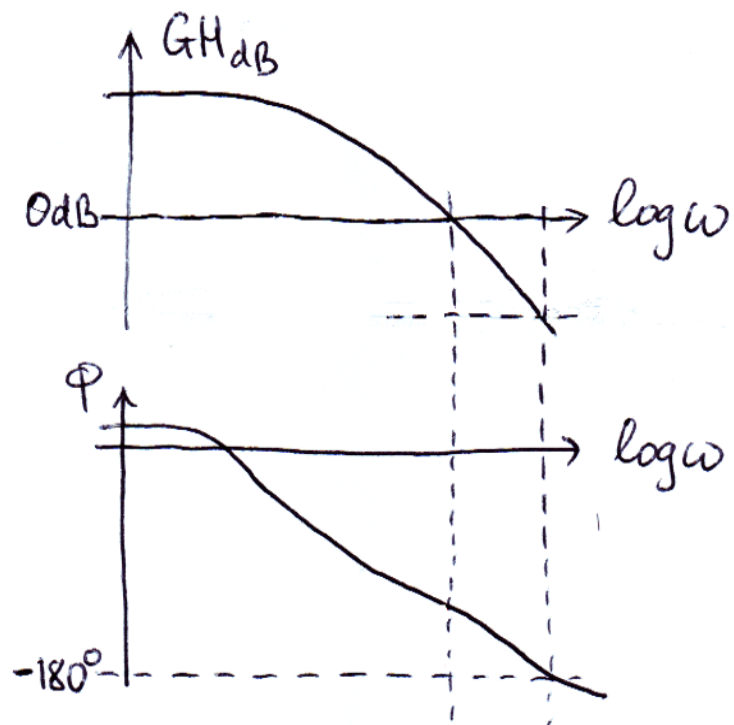


$$H' = \frac{Z_1}{Z_2}$$

$$G_{CL} = \frac{1}{H} \frac{1}{1 + \frac{1}{GH}}$$

$$G_{CL} = -\frac{1}{H'} \frac{1}{\left(1 + \frac{1}{G}\right) + \frac{1}{GH'}} \quad (4)$$

### Phase & gain margins



### Nyquist plots



Nyquist criterion of stability: