

Gauge Invariance in the Eikonal Method

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The eikonal method of charged particle optics requires a multipole expansion of the magnetic vector potential. A procedure is outlined which allows a direct computation of the vector potential from the multipole expansion of the magnetic scalar potential. It is shown how the vector potential and the eikonal adopt a simple form by choosing a suitable gauge.

1 Introduction

In electron microscopy and accelerator physics the motion of particles near a reference curve is of interest. To describe the properties of such a particle optical device, the coordinates \vec{z}_f in the end plane of the device have to be expressed as a function of the initial coordinates \vec{z}_i :

$$\vec{z}_f = \mathcal{M}(\vec{z}_i) . \quad (1)$$

The components of \vec{z} are the space coordinates \vec{r} and the vector components of the canonical momentum \vec{p} . It is useful to expand this function or map \mathcal{M} in a Taylor series about a central curve. This can be done by evaluating the equation of motion in Taylor expansions [1] or more effectively by using the eikonal method which yields simpler formulas and automatically satisfies the symplectic condition [2].

It is advantageous to describe the electric and the magnetic field by scalar potentials and to expand the potentials in plane multipoles about the reference curve [3] because the multipole coefficients are experimentally accessible. The magnetic vector potential \vec{A} is needed for calculating the eikonal

$$S = \int_{\text{path}} \vec{p} d\vec{s} = \int_{\text{path}} (m\vec{v} + q\vec{A}) d\vec{s} \quad (2)$$

where $d\vec{s}$ is an element of the path taken by a particle with kinematic momentum $m\vec{v}$ and charge q . In the traditional way the computation of the vector potential is one of the most cumbersome parts of deriving expansion coefficients of \mathcal{M} by the eikonal method.

Recently it has been pointed out [2] that the procedure to compute the vector potential from the scalar potential can be simplified considerably by choosing a suitable gauge function. A mistake mentioned in [4] will be corrected and the method will be explained in detail.

2 Curvilinear coordinates and complex notation

The coordinates near the central curve of reference will be written in complex notation. A space point near this reference curve is described by a vector with three components. Let z be the path length of this curve. Then all space points which lie on a plane perpendicular to the reference curve have the same z -component. In this plane we introduce a rectangular cartesian x, y coordinate system. The x -axis is located in the horizontal plane as depicted in Fig.1a. For mathematical simplicity it is advantageous to describe the off-axial position by the complex coordinates

$$w = x + iy \quad , \quad \bar{w} = x - iy \quad . \quad (3)$$

The metric coefficients of the curvilinear coordinate system shown in Fig.1b are

Place for Fig.1

$$g_1 = \left| \frac{d\vec{r}}{dx} \right| = 1 \quad , \quad g_2 = \left| \frac{d\vec{r}}{dy} \right| = 1 \quad , \quad g_3 = \left| \frac{d\vec{r}}{dz} \right| = \left| \frac{\rho^2 - \vec{r}\vec{\rho}}{\rho^2} \right| \quad (4)$$

where ρ is the local radius of curvature of the reference curve. The last relation is simplified by using the complex curvature

$$\Gamma = \frac{\rho_x + i\rho_y}{\rho^2} \quad , \quad g_3 = h = 1 - \Re\{\bar{w}\Gamma\} \quad . \quad (5)$$

The partial derivatives ∂_x, ∂_y with respect to the coordinates x and y are related to the partial derivatives with respect to the complex coordinates w and \bar{w} via the formulas

$$\begin{aligned} \partial_x &= 2\Re\{\partial_w\} \quad , \quad \partial_y = -2\Im\{\partial_w\} \quad , \\ \partial_w &= \frac{1}{2}(\partial_x - i\partial_y) \quad , \quad \partial_{\bar{w}} = \frac{1}{2}(\partial_x + i\partial_y) \end{aligned} \quad (6)$$

where $\Re\{\dots\}$ and $\Im\{\dots\}$ denote the real and imaginary part, respectively.

3 The magnetic scalar potential

In the case of static fields the magnetic field $\vec{B}(\vec{r})$, at a point \vec{r} without electrical current, can be derived from a magnetic scalar potential $\psi(\vec{r})$:

$$\vec{B}(\vec{r}) = -\nabla\psi(\vec{r}) \quad (7)$$

where $\psi(\vec{r})$ satisfies the Laplace equation

$$\nabla^2\psi(\vec{r}) = 0. \quad (8)$$

By employing the complex notation introduced in section 2 the Laplace equation in the curvilinear coordinate system adopts the form

$$\nabla^2\psi = \frac{1}{h}\{2\partial_w(h\partial_{\bar{w}}\psi) + 2\partial_{\bar{w}}(h\partial_w\psi) + \partial_z(\frac{1}{h}\partial_z\psi)\} = 0. \quad (9)$$

The solution can be expanded in a power series about an arbitrary curve. The expansion coefficients [5, 3, 6] have an intuitive meaning. A field of symmetry C_ζ about the reference curve which does not vary with the path length z has the potential $\psi = \Re\{\Psi_\zeta\bar{w}^\zeta\}$ because this harmonic polynomial satisfies the Laplace equation and the required symmetry. The multipole coefficient Ψ_ζ of symmetry C_ζ is generally complex. Its phase describes the orientation of the multipole with respect to the x, y coordinate system. Therefore rotational symmetric fields are described by the real multipole coefficient Ψ_0 . If the field varies with path length z , a power series expansion

$$\psi(\vec{r}) = \Re\left\{\sum_{\zeta}^{\infty}\sum_{\lambda}^{\infty}a_{\zeta\lambda}(z)(w\bar{w})^\lambda\bar{w}^\zeta\right\} \quad (10)$$

exists where the multipole coefficients

$$a_{\zeta 0}(z) = \Psi_\zeta(z) \quad (11)$$

are functions of the z -coordinate. In the case of a straight reference curve the Laplace equation yields

$$4\lambda(\lambda + \zeta)a_{\zeta\lambda} + \partial_z^2 a_{\zeta\lambda-1} = 0, \quad (12)$$

$$a_{\zeta\lambda} = (-1)^\lambda \frac{\zeta!}{\lambda!(\lambda + \zeta)!} \left(\frac{1}{4}\right)^\lambda \partial_z^{[2\lambda]}\Psi_\zeta. \quad (13)$$

For an arbitrary curvature Γ a recursion formula can also be derived [3]. Therefore the multipole coefficients $\Psi_\zeta(z)$ uniquely characterize the expansion (10) provided they are analytic functions of z .

4 The magnetic vector potential

The relation between a specific vector potential $\vec{A}^*(\vec{r})$ and the scalar potential $\psi(\vec{r})$ follows from the identity

$$\vec{B}(\vec{r}) = \nabla \times (\vec{A}^*(\vec{r}) + \nabla\Lambda(\vec{r})) = -\nabla\psi(\vec{r}) \quad (14)$$

where $\Lambda(\vec{r})$ denotes an arbitrary real scalar gauge function. Using the complex notation, the z -component of the magnetic field $\vec{B}(\vec{r})$ has the form

$$B_z = -\frac{1}{h}\partial_z\psi = -2\Im\{\partial_{\bar{w}}(\bar{A}^* + 2\partial_w\Lambda)\} = 2\Re\{i\partial_{\bar{w}}(\bar{A}^* + 2\partial_w\Lambda)\} \quad (15)$$

with $A^* = A_x^* + iA_y^*$. For an arbitrary real scalar function $\chi(\vec{r})$ the gauge function will be chosen such that

$$-\frac{1}{h}\partial_z\chi = 2\Im\{i\partial_{\bar{w}}(\bar{A}^* + 2\partial_w\Lambda)\} \quad (16)$$

which implies that the gauge function satisfies

$$4\partial_w\partial_{\bar{w}}\Lambda = -\frac{1}{h}\partial_z\chi - 2\Re\{\partial_{\bar{w}}\bar{A}^*\} . \quad (17)$$

With this choice of gauge we obtain from equation (14)

$$-\frac{1}{h}\partial_z(\psi + i\chi) = 2i\partial_{\bar{w}}\bar{A} , \quad (18)$$

$$2ih\partial_w\psi = -\partial_z\bar{A} + 2\partial_w(hA_z) . \quad (19)$$

Here $\vec{A} = \vec{A}^* + \nabla\Lambda$ denotes the vector potential in the new gauge. We choose $\chi(\vec{r})$ as an arbitrary solution of the Laplace equation

$$2\partial_w\{h\partial_{\bar{w}}(\psi + i\chi)\} + 2\partial_{\bar{w}}\{h\partial_w(\psi + i\chi)\} + \partial_z\{\frac{1}{h}\partial_z(\psi + i\chi)\} = 0 . \quad (20)$$

The linear combination $\Pi = \psi + i\chi$ has been defined as complex scalar potential [2]. Here we want to stress the crucial point $\Im\{\nabla^2\Pi\} = 0$. Only because of the specific choice (17) of the gauge function we were able to deduce the simple equation (18) which can be integrated directly:

$$\bar{A} = \frac{i}{2} \int_0^{\bar{w}} \frac{1}{h} \partial_z(\psi + i\chi) d\bar{w} + f(z, w) \quad (21)$$

where f is an arbitrary function which does not depend on \bar{w} . Inserting \bar{A} into equation (19) and employing the Laplace equation (20), we obtain

$$\begin{aligned}\partial_w(hA_z) &= ih\partial_w\psi + \frac{i}{4}\int_0^{\bar{w}}[-2\partial_w\{h\partial_{\bar{w}}(\psi+i\chi)\} - 2\partial_{\bar{w}}\{h\partial_w(\psi+i\chi)\}]d\bar{w} \\ &+ \frac{1}{2}\partial_z f(z, w) .\end{aligned}\quad (22)$$

This relation can be directly integrated over w . The boundaries of the integration must be taken into account very carefully by considering relations such as $\int_0^{\bar{w}}\partial_{\bar{w}}\{h\partial_w(\psi+i\chi)\}d\bar{w} = h\partial_w(\psi+i\chi) - [h\partial_w(\psi+i\chi)]_{\bar{w}=0}$. Moreover, the order of integration with respect to w and \bar{w} must be exchanged. As a result we find

$$\begin{aligned}hA_z &= i\int_0^w h\partial_w\psi dw - \frac{i}{2}\int_0^w\{h\partial_w(\psi+i\chi) - [h\partial_w(\psi+i\chi)]_{\bar{w}=0}\}dw \\ &- \frac{i}{2}\int_0^{\bar{w}}h\partial_{\bar{w}}(\psi+i\chi)d\bar{w} + \frac{1}{2}\int_0^w\partial_z f(z, w)dw + g(z, \bar{w}) .\end{aligned}\quad (23)$$

Integrating by parts and inserting the definition (5) of h yields

$$\begin{aligned}hA_z &= ih\psi - \frac{i}{2}\{h(\psi+i\chi) - [h(\psi+i\chi)]_{\bar{w}=0}\} - \frac{i}{2}\int_0^{\bar{w}}\partial_{\bar{w}}\{h(\psi+i\chi)\}d\bar{w} \\ &+ \frac{i}{2}\bar{\Gamma}\int_0^w\psi dw - \frac{i}{4}\bar{\Gamma}\int_0^w\{(\psi+i\chi) - [\psi+i\chi]_{\bar{w}=0}\}dw \\ &- \frac{i}{4}\Gamma\int_0^{\bar{w}}(\psi+i\chi)d\bar{w} + \frac{1}{2}\int_0^w\partial_z f(z, w)dw + k(z, \bar{w})\end{aligned}\quad (24)$$

where $g(z, \bar{w})$ and $k(z, \bar{w})$ are arbitrary analytical functions of z and \bar{w} . By rearranging the terms on the right-hand side we obtain

$$\begin{aligned}hA_z &= h\chi + \frac{1}{2}\frac{1}{2i}\{\Gamma\int_0^{\bar{w}}(\psi+i\chi)d\bar{w} - \bar{\Gamma}\int_0^w(\psi-i\chi)dw\} \\ &+ i[h(\psi+i\chi)]_{\bar{w}=0} + \frac{i}{4}\bar{\Gamma}\int_0^w[\psi+i\chi]_{\bar{w}=0}dw\end{aligned}$$

$$+ \frac{1}{2} \int_0^w \partial_z f(z, w) dw + k(z, \bar{w}) . \quad (25)$$

The arbitrary functions f and k must be chosen in such a way that the right-hand side of (25) is a real function. The part

$$i[h(\psi + i\chi)]_{\bar{w}=0} + \frac{i}{4} \bar{\Gamma} \int_0^w [\psi + i\chi]_{\bar{w}=0} dw \quad (26)$$

is only a function of z and w . Therefore $k(z, \bar{w})$ can be chosen to be the complex conjugate of this function. It is not possible to simplify the expressions with another choice than $f = 0$. With this we obtain

$$\bar{A} = \frac{i}{2} \int_0^{\bar{w}} \frac{1}{h} \partial_z (\psi + i\chi) d\bar{w} , \quad (27)$$

$$\begin{aligned} hA_z &= h\chi + \frac{1}{2} \Im \left\{ \Gamma \int_0^{\bar{w}} (\psi + i\chi) d\bar{w} \right\} \\ &- 2\Im \{ [h(\psi + i\chi)]_{\bar{w}=0} \} - \frac{1}{2} \Im \left\{ \bar{\Gamma} \int_0^w [\psi + i\chi]_{\bar{w}=0} dw \right\} . \end{aligned} \quad (28)$$

With the knowledge of the magnetic vector potential and equation (2) we can compute the eikonal by integrating along a path $\vec{s}(z)$ that starts at $\vec{s}(z_0)$:

$$S = \int_{\text{path}} (m\vec{v} + q\vec{A}) d\vec{s} = m_0 c \int_{z_0}^z \mu(z) dz \quad (29)$$

with the rest mass m_0 . The right-hand side defines the variational function:

$$\mu(z) = \frac{1}{m_0 c} (mv + q\vec{A}\vec{t}) \frac{ds}{dz} \quad (30)$$

with the differential path length $ds = |d\vec{s}|$ and the tangent $\vec{t} = d\vec{s}/ds$. In complex notation the path is described by $w(z), \bar{w}(z)$ such that the variational function is written

$$\mu = \frac{mv}{m_0 c} \sqrt{h^2 + w'\bar{w}'} + \frac{q}{m_0 c} (\Re\{w'\bar{A}\} + hA_z) \quad (31)$$

with $w' = dw/dz$. Because of the equations (27) and (28) this is equivalent to

$$\begin{aligned}
\mu &= \frac{mv}{m_0c} \sqrt{h^2 + w'\bar{w}'} \\
&+ \frac{q}{m_0c} \left[h\chi - \frac{1}{2} \Im \left\{ w' \int_0^{\bar{w}} \frac{1}{h} \partial_z (\psi + i\chi) d\bar{w} \right\} \right. \\
&+ \frac{1}{2} \Im \left\{ \Gamma \int_0^{\bar{w}} (\psi + i\chi) d\bar{w} \right\} - 2 \Im \left\{ [h(\psi + i\chi)]_{\bar{w}=0} \right\} \\
&\left. - \frac{1}{2} \Im \left\{ \bar{\Gamma} \int_0^w [(\psi + i\chi)]_{\bar{w}=0} dw \right\} \right]. \tag{32}
\end{aligned}$$

The advantage of the formulas (27), (28) and (32) arises from the fact that no integration over the path length z is required. The necessary integrations with respect to w and \bar{w} are straightforward integrations of Taylor series which can be performed to arbitrary order by formula manipulators or DA programs.

Since the only constraint on the function $\chi(\vec{r})$ is that it has to fulfill the Laplace equation this function can be expanded in a series of plane multipoles whose coefficients $\chi_\zeta(z)$ can be chosen arbitrarily. With definition (10) and (11) we get

$$[\psi + i\chi]_{\bar{w}=0} = \frac{1}{2} \sum_{\zeta=1}^{\infty} (\bar{\Psi}_\zeta + i\bar{\chi}_\zeta) w^\zeta + \Psi_0 \tag{33}$$

where it was considered that Ψ_0 is real. The following choice simplifies the expansion for \vec{A} :

$$\chi_\zeta = -i\Psi_\zeta \text{ for } \zeta \neq 0, \quad \chi_0 = 0 \quad \Rightarrow \quad [\psi + i\chi]_{\bar{w}=0} = \Psi_0 \tag{34}$$

which yields:

$$\begin{aligned}
\bar{A} &= \frac{i}{2} \int_0^{\bar{w}} \frac{1}{h} \partial_z (\psi + i\chi) d\bar{w}, \tag{35} \\
hA_z &= h\chi + \frac{1}{2} \Im \left\{ \Gamma \int_0^{\bar{w}} [(\psi + i\chi) - \Psi_0] d\bar{w} \right\}.
\end{aligned}$$

For the chosen gauge (34) the expansion of the complex scalar potential in plane multipoles has the form

$$\begin{aligned}
\Pi = \psi + i\chi &= \Psi_0 & (36) \\
&+ \Psi_1 \bar{w} \\
&+ \Psi_2 \bar{w}^2 + \frac{1}{4}(\Psi_1 \bar{\Gamma} - \Psi_0'') w \bar{w} \\
&+ \Psi_3 \bar{w}^3 + \frac{1}{8}(2\Psi_2 \bar{\Gamma} - \Psi_1'') w \bar{w}^2 \\
&+ \frac{3}{16} \Psi_1 \Re\{\Gamma w \bar{w}^2\} \bar{\Gamma} - \frac{1}{16} \Re\{(5\Psi_0'' \Gamma + 2\Psi_0' \Gamma') w \bar{w}^2\} \\
&+ \dots
\end{aligned}$$

This expansion corrects equation (54) of [2]. Since the incorrect expression for the complex scalar potential has been used in that publication, equation (60) and (61) of [2] are also erroneous and must be replaced by the correct formulas for the components of the magnetic vector potential:

$$\begin{aligned}
\bar{A} &= \frac{i}{2} [\Psi_0' \bar{w} & (37) \\
&+ \frac{1}{2} \{(\Psi_1' + \frac{1}{2} \Psi_0' \Gamma) \bar{w}^2 + \Psi_0' \bar{\Gamma} w \bar{w}\} \\
&+ \frac{1}{12} (4\Psi_2' + 2\Psi_1' \Gamma + \Psi_0' \Gamma^2) \bar{w}^3 + \frac{1}{4} \Psi_0' \bar{\Gamma}^2 w^2 \bar{w} \\
&+ \frac{1}{8} (\Psi_1 \bar{\Gamma}' + 3\Psi_1' \bar{\Gamma} + 2\Psi_0' \Gamma \bar{\Gamma} - \Psi_0''') w \bar{w}^2] \\
&+ \dots, \\
hA_z &= \Im\{\Psi_1 \bar{w}\} & (38) \\
&+ \Im\{(\Psi_2 - \frac{1}{4} \Psi_1 \Gamma) \bar{w}^2 - \frac{1}{4} \Psi_1 \bar{\Gamma} w \bar{w}\} \\
&+ \Im\{(\Psi_3 - \frac{1}{3} \Psi_2 \Gamma) \bar{w}^3 \\
&\quad + \frac{1}{32} (-8\Psi_2 \bar{\Gamma} + \bar{\Psi}_1 \Gamma^2 + \Psi_1 \Gamma \bar{\Gamma} - 4\Psi_1'' - 2\Psi_0'' \Gamma) w \bar{w}^2\} \\
&+ \dots
\end{aligned}$$

The gauge $\chi = 0$ yields the simplest variational function:

$$\mu = \frac{mv}{m_0 c} \sqrt{h^2 + w' \bar{w}'} - \frac{q}{m_0 c} \left[\frac{1}{2} \Im \left\{ w' \int_0^{\bar{w}} \frac{1}{h} \partial_z \psi d\bar{w} \right\} \right] \quad (39)$$

$$- \frac{1}{2} \Im \left\{ \Gamma \int_0^{\bar{w}} \psi d\bar{w} \right\} + \frac{1}{2} \Im \left\{ \bar{\Gamma} \int_0^w [\psi]_{\bar{w}=0} dw \right\} + 2 \Im \{ [h\psi]_{\bar{w}=0} \} .$$

With this formula μ can be computed to order $n + 1$ if the multipole expansion of scalar potentials is known to order n . The reason for this fact is that the $(n + 1)^{th}$ order expansion of $[h\psi]_{\bar{w}=0}$ is trivially

$$[h\psi]_{\bar{w}=0} = \left(1 - \frac{1}{2} \bar{\Gamma} w \right) \left(\frac{1}{2} \sum_{\zeta=1}^{\infty} \bar{\Psi}_{\zeta} w^{\zeta} + \Psi_0 \right) . \quad (40)$$

Of course, the variational function of the eikonal method depends on the choice of the function $\chi(\vec{r})$ because the Lagrangian is not gauge invariant. Nevertheless, it was proved in [7] that the transfer function or map from the initial to the final plane, calculated by the eikonal method, does not depend on the gauge.

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Figure caption

Figure 1: a) The curvilinear coordinate system, b) derivation of the metric coefficient $g_3 = |d\vec{r}/dz|$ at a point where the reference curve has a curvature of $1/\rho$.