



Optimization of HOM Couplers using Time Domain Schemes

Workshop on HOM Damping in Superconducting RF Cavities

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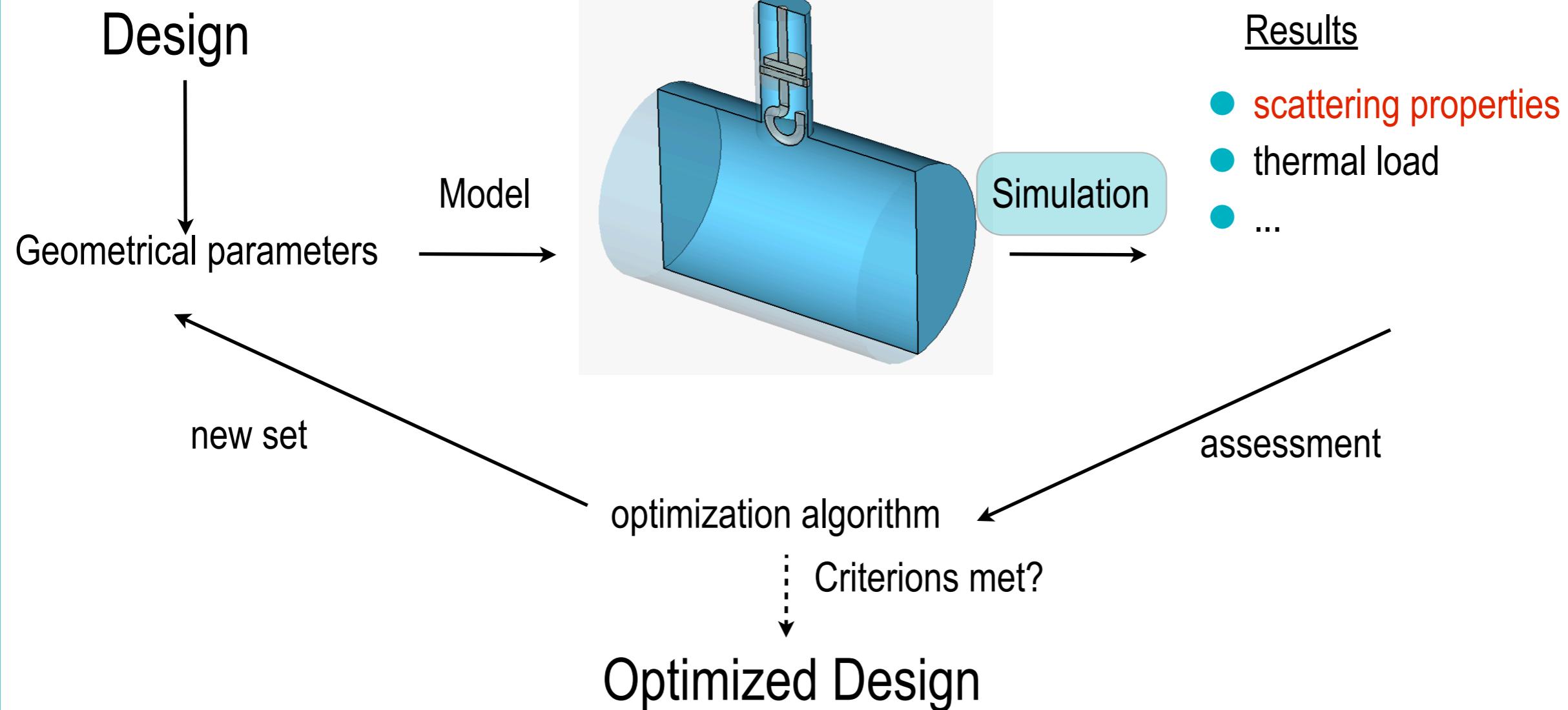


Overview

- Introduction
- Comparison of selected numerical time domain schemes
- Application Example: Optimization of the filter characteristics of a preliminary HOM coupler design with SPL dimensions.
- Conclusions



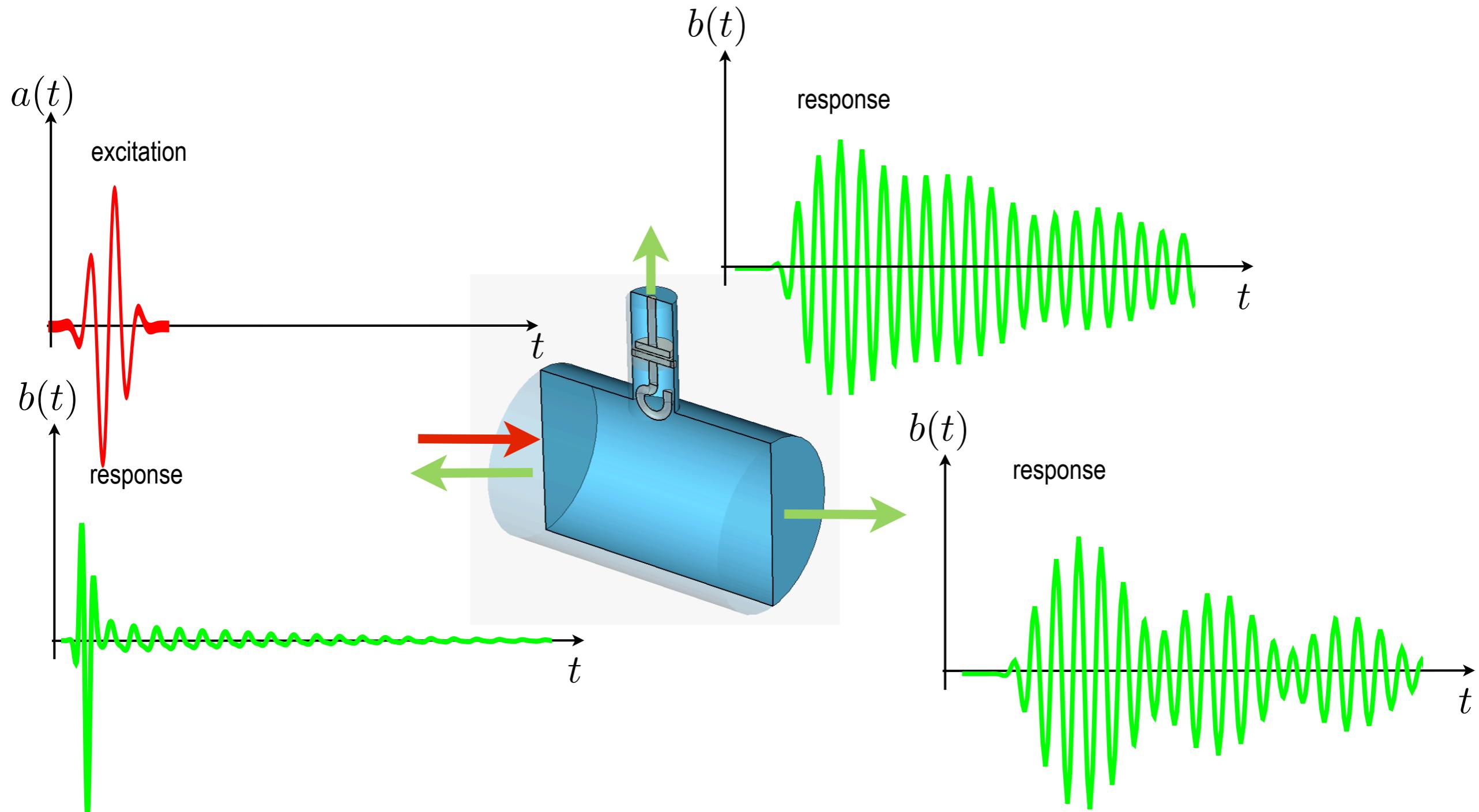
Introduction - Numerical Optimization



- Simulation is (in general) the most time consuming part
- Use as few simulations as possible and a **suited numerical scheme!**

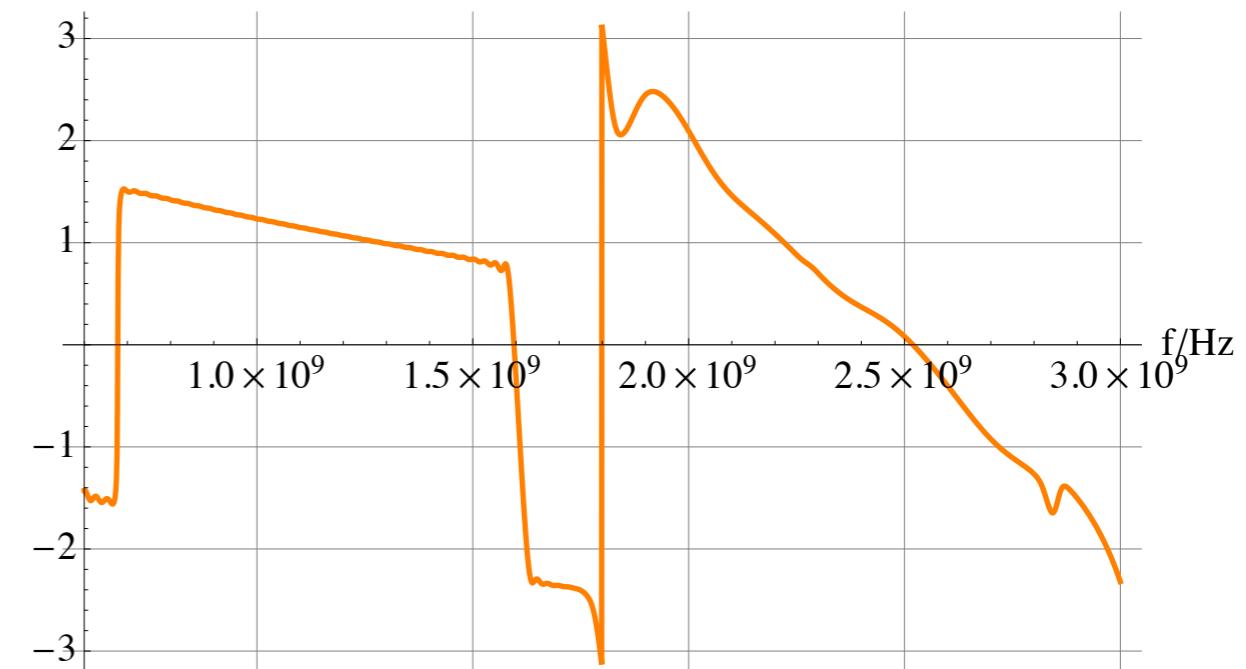
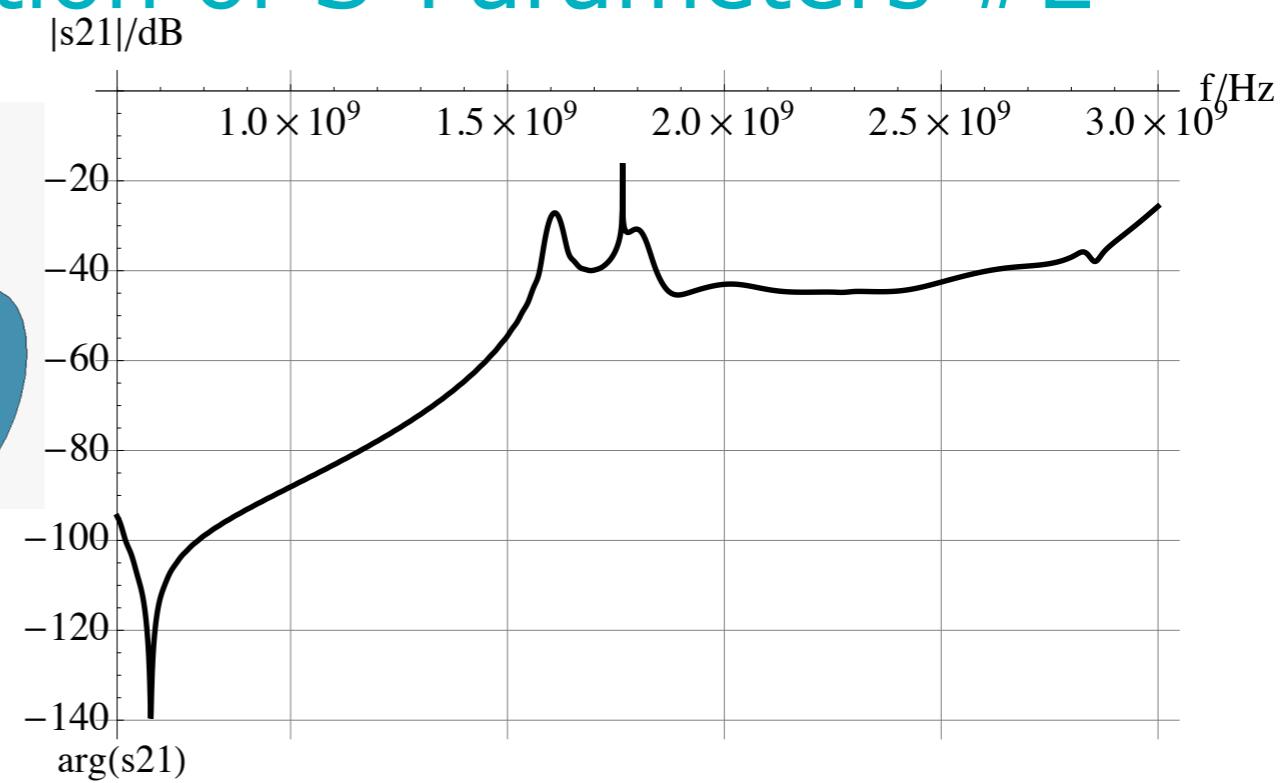
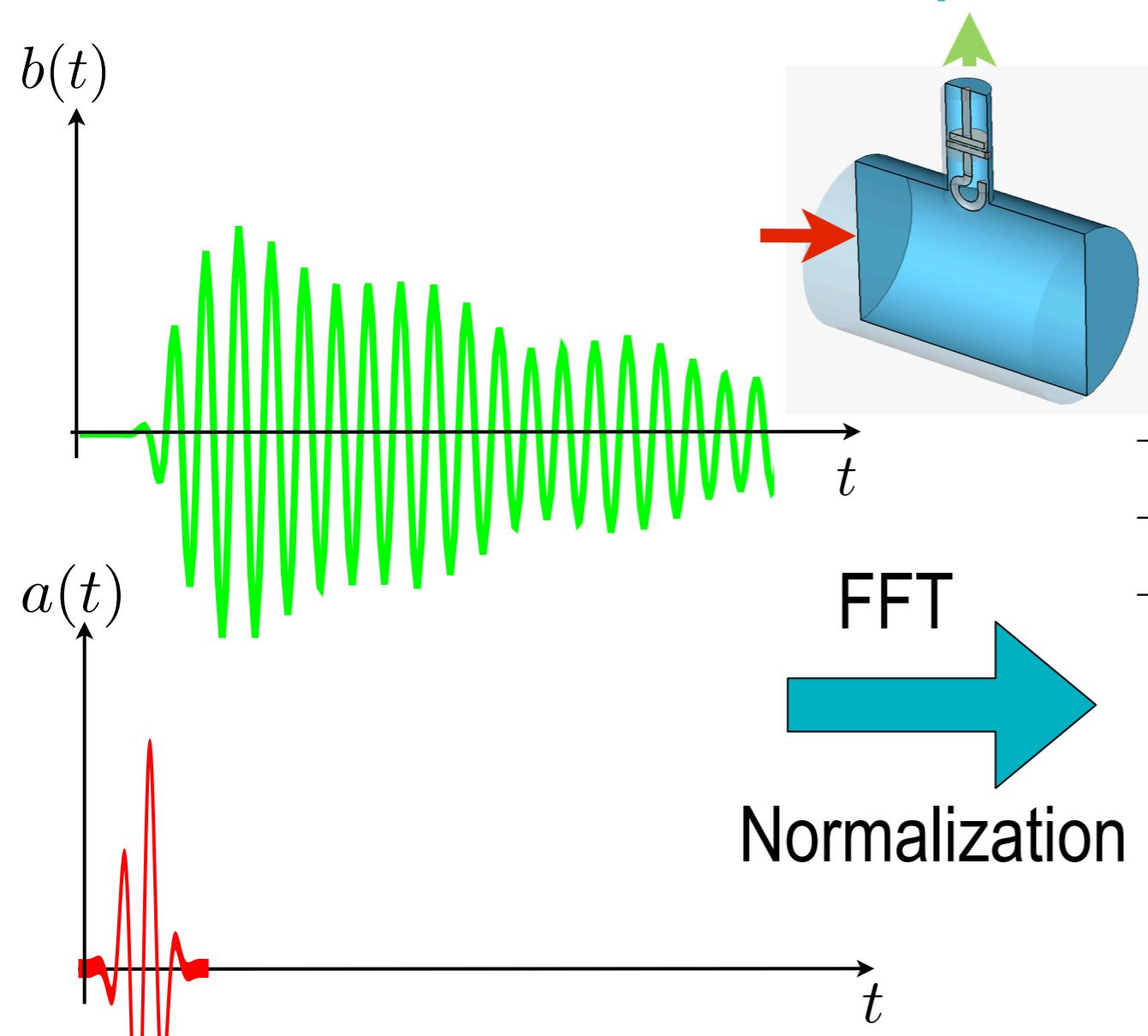


Time Domain Computation of S-Parameters #1





Time Domain Computation of S-Parameters #2

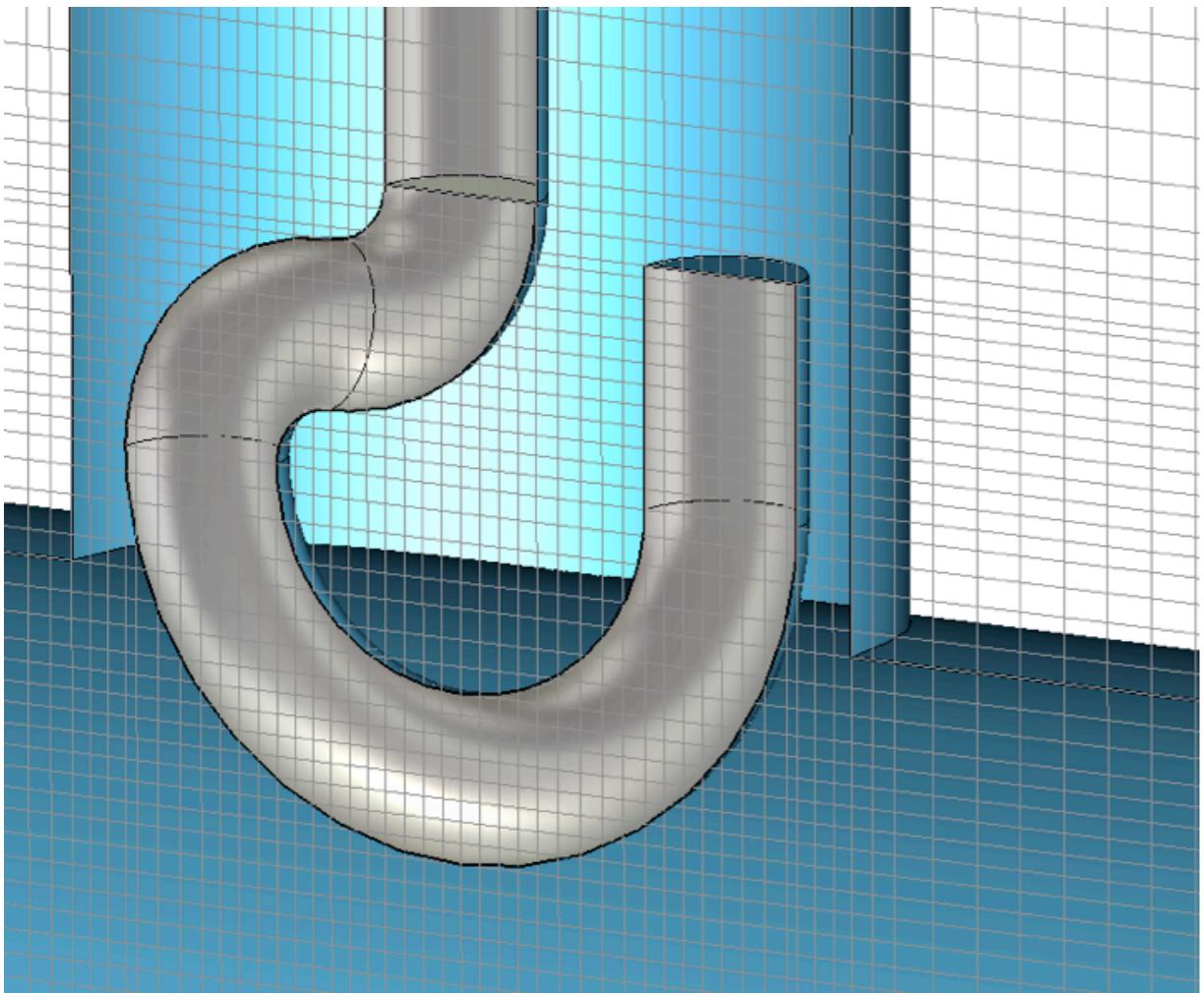




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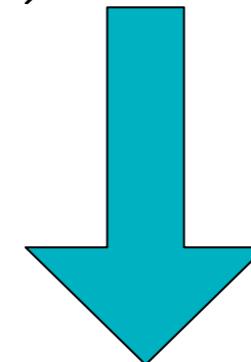
Numerical Schemes - „Stencil“ Approach



HOM section and cartesian grid

- FDTD/FIT
- Commonly used on regular grids (orthogonality!)
- Compute fields/fluxes at a location by surrounding fields/fluxes (linear operators L₁,L₂)
- Explicit update equation for discrete field vectors ($\underline{e}, \underline{h}$):

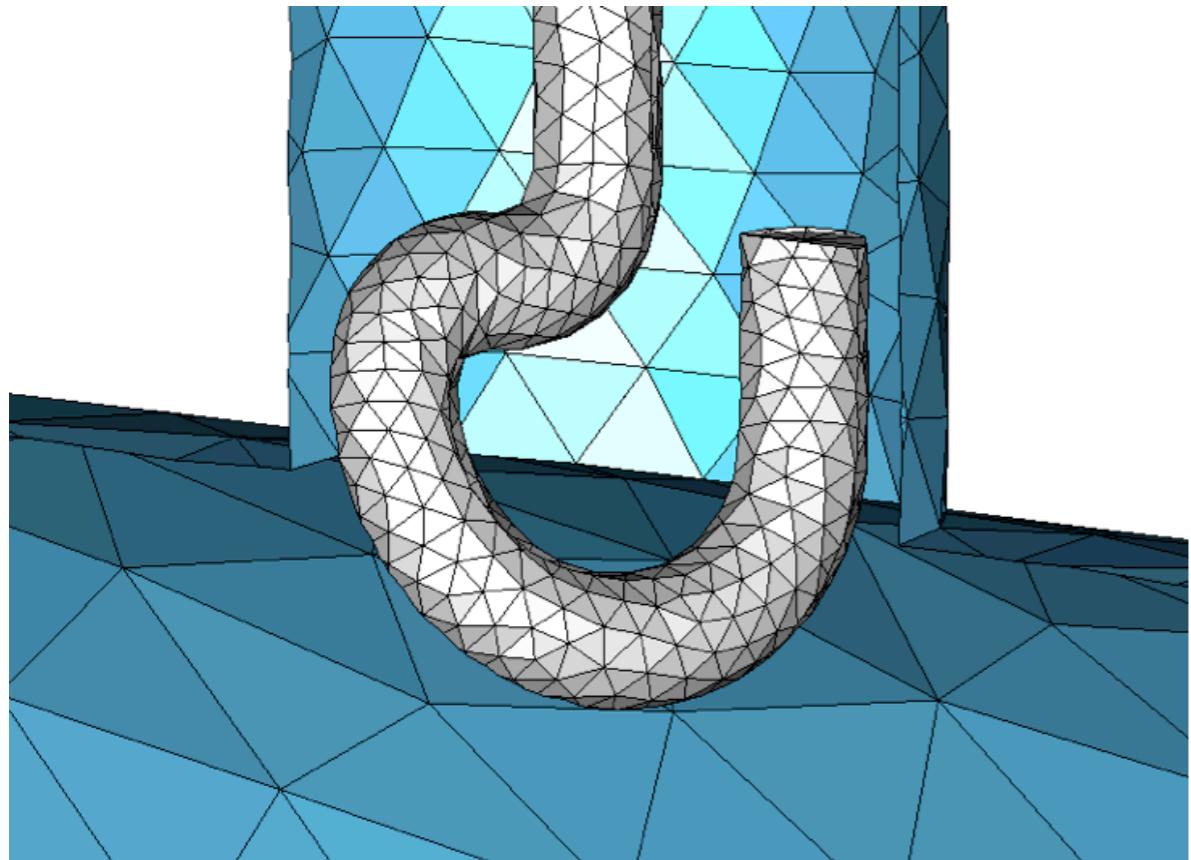
$$\frac{d}{dt} \begin{pmatrix} \underline{e} \\ \underline{h} \end{pmatrix} = \begin{pmatrix} L_1(\underline{e}, \underline{h}) \\ L_2(\underline{e}, \underline{h}) \end{pmatrix}$$



Explicit but limited geometric flexibility.



FEM Approach



HOM section discretized unstructured tetrahedral grid
(coarse)

- Allows for unstructured grids => suited for complex curved structures and a reasonable number of elements/dofs
- Project fields on a finite function space, compute inner product with test functions (commonly used approach: Galerkin)
- Problem: Leads to implicit semi-discrete formulation (unless problem is sufficiently small and mass matrices can be inverted)

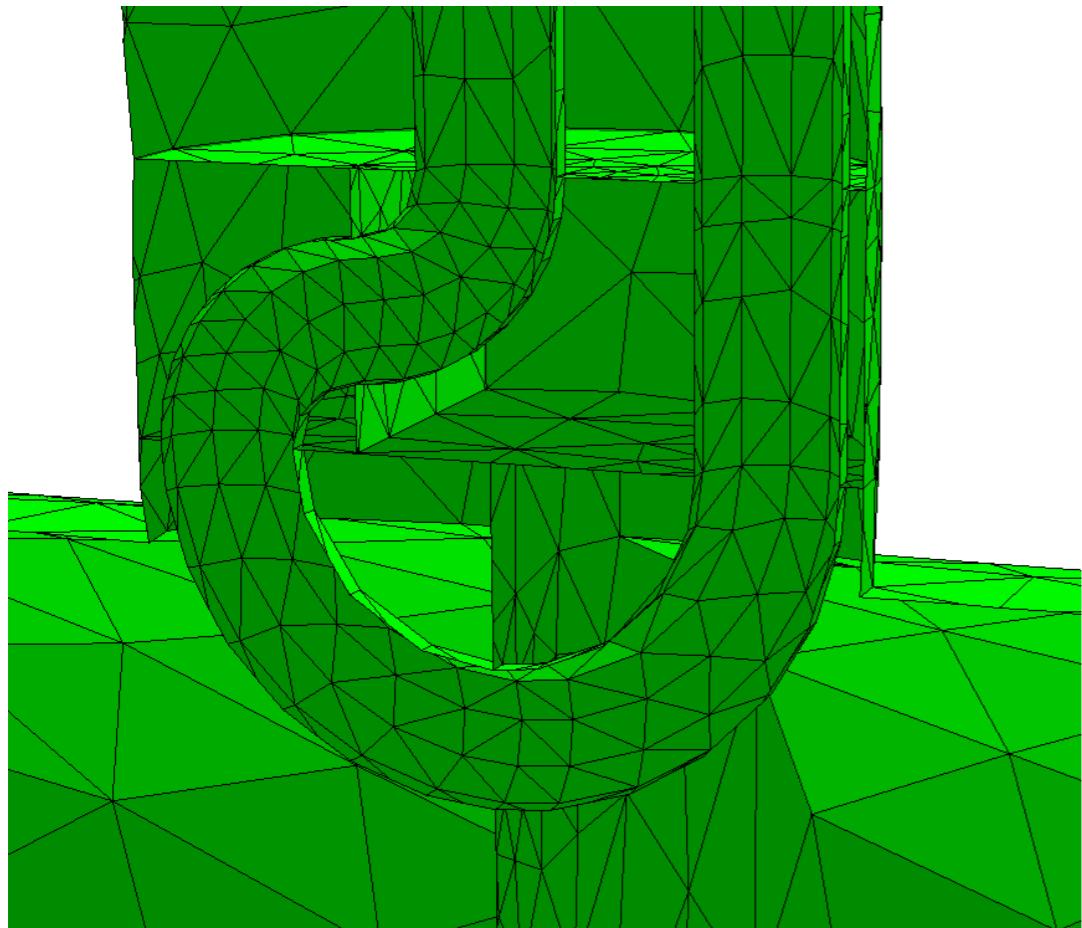
$$\frac{d}{dt} \begin{pmatrix} \underline{\underline{M}}_1 \underline{e} \\ \underline{\underline{M}}_2 \underline{h} \end{pmatrix} = \underline{\underline{S}} \begin{pmatrix} \underline{h} \\ \underline{e} \end{pmatrix}$$

Global matrices

Geometrical flexibility but implicit.



Discontinuous Galerkin (DG) - FEM Approach #1



HOM section discretized (12k elements, second order)

- Allows for unstructured grids => suited for complex curved structures
- Support of basis and test functions is limited to the individual corresponding elements
- Adjacent elements connected by boundary fluxes
- All matrices defined element wise => small
- Matrix inversion is feasible => explicit
- „Parallel by design“

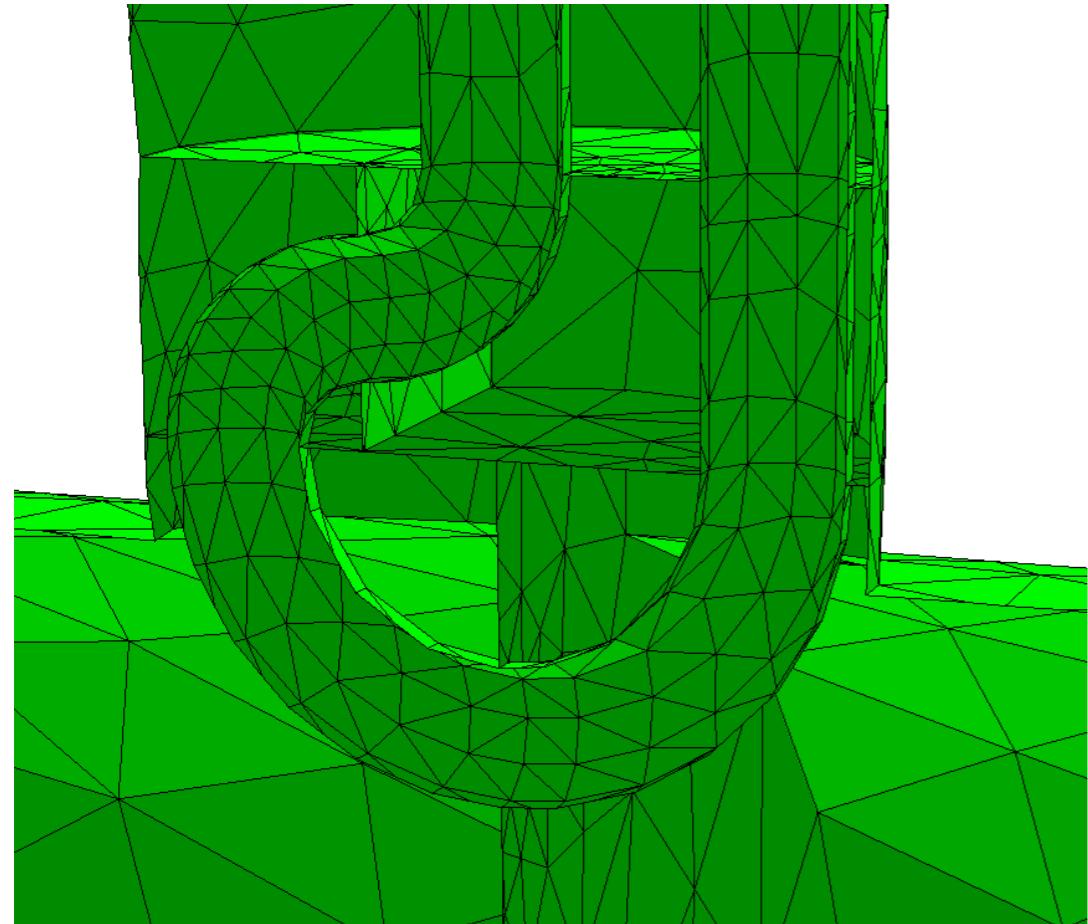
$$\frac{d}{dt} \begin{pmatrix} \underline{e} \\ \underline{h} \end{pmatrix} = \underline{\underline{M}}^{-1} \underline{\underline{S}} \begin{pmatrix} \varepsilon^{-1} \underline{h} \\ -\mu^{-1} \underline{e} \end{pmatrix} + \underline{\underline{M}}^{-1} \underline{\underline{F}} \begin{pmatrix} \varepsilon^{-1} \hat{\underline{n}} \times \underline{f}_H \\ \mu^{-1} \hat{\underline{n}} \times \underline{f}_E \end{pmatrix}$$

↑ element wise matrices ↓ coupling of adjacent elements

Geometrical flexibility and explicit.

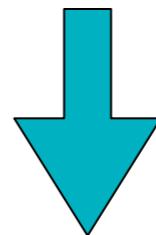


Discontinuous Galerkin (DG) - FEM Approach #2



HOM section discretized (12k elements, second order)

- Our S-Parameter code is based on NUDG* framework
- NUDG* framework (open source) implements basic operators, time integrator,...
- We added: boundary conditions (broadband waveguide excitation and absorption), improved PML, modal analysis, ..., pre- and post processing
=> on graphic card (GPU - NVIDIA CUDA based)



Why graphic cards?

* www.nudg.org



Theoretical
GFLOP/s
1500

Why GPUs?

- NVIDIA GPU Single Precision
- NVIDIA GPU Double Precision
- Intel CPU Single Precision
- Intel CPU Double Precision

Modern GPUs heavily outperform modern CPUs!



- Up to 1.5 TFlops / GPU (single precision)
- cheap (350 € /Unit)
- Highly scalable => multiple GPU/Workstation or GPU clusters
- Well suited for highly parallel algorithms like Discontinuous Galerkin FEM

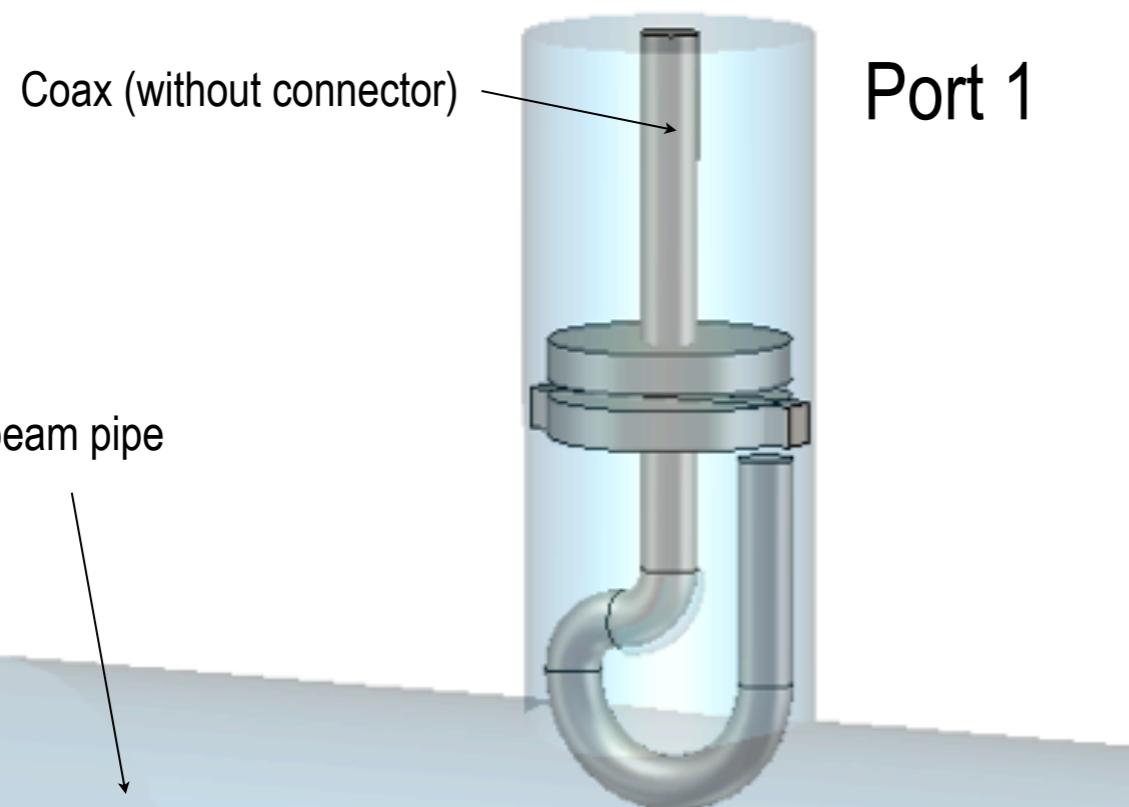
Comparison theoretical GFLOP/s GPU vs. CPU (source: NVIDIA)



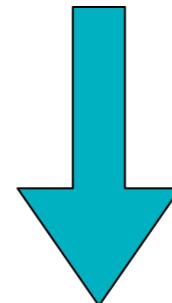
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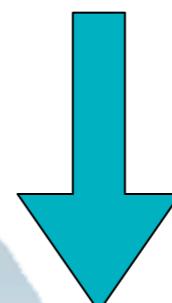
Application Example: HOM coupler with SPL geometric properties



- Tuning of filter characteristics



- „Notch effect“ @ 704.4 MHz
(SPL fundamental mode)

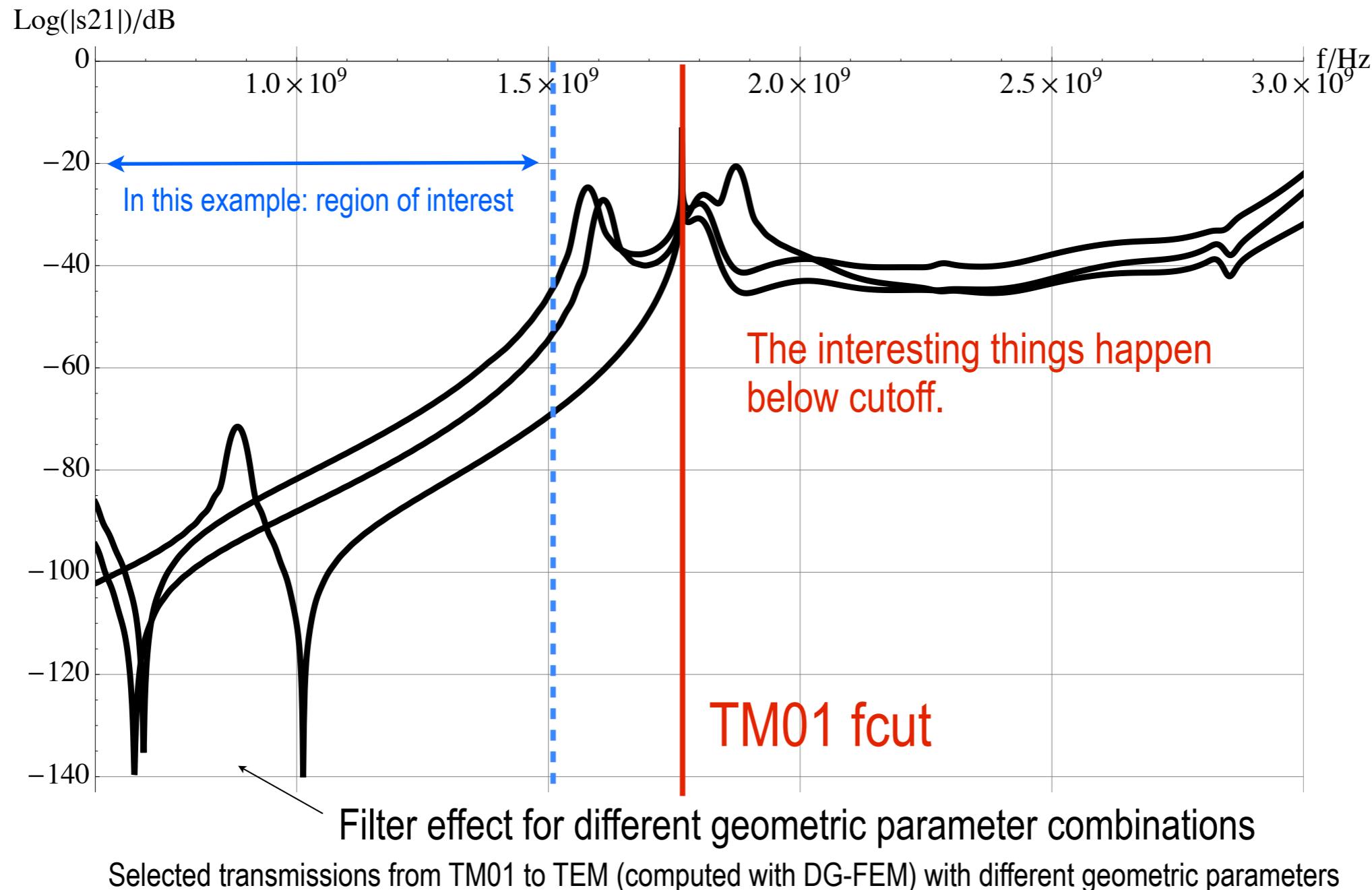


- Which scheme to use for optimization?

(Preliminary) Model of a HOM coupler/beam pipe section with SPL specs.

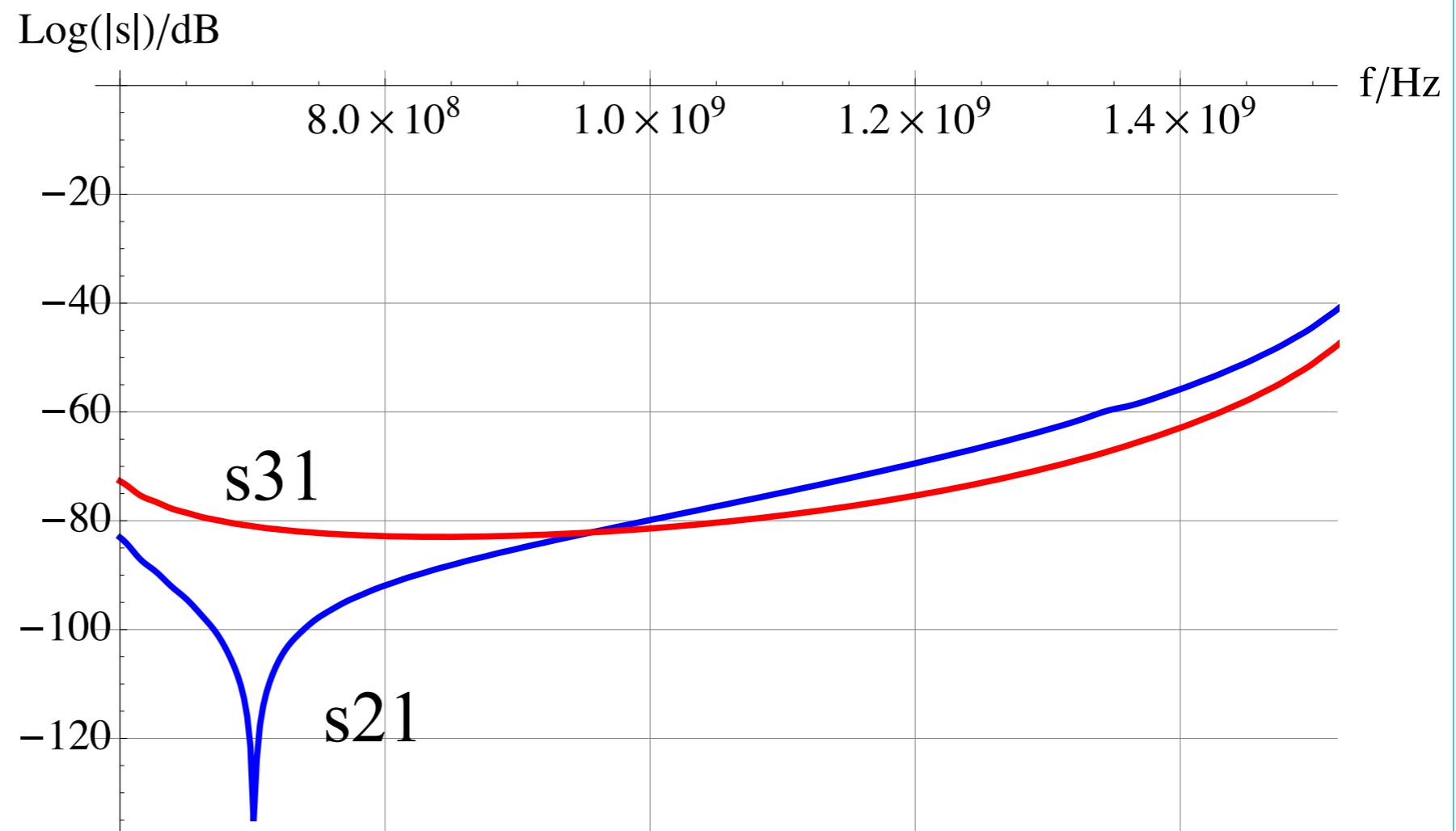
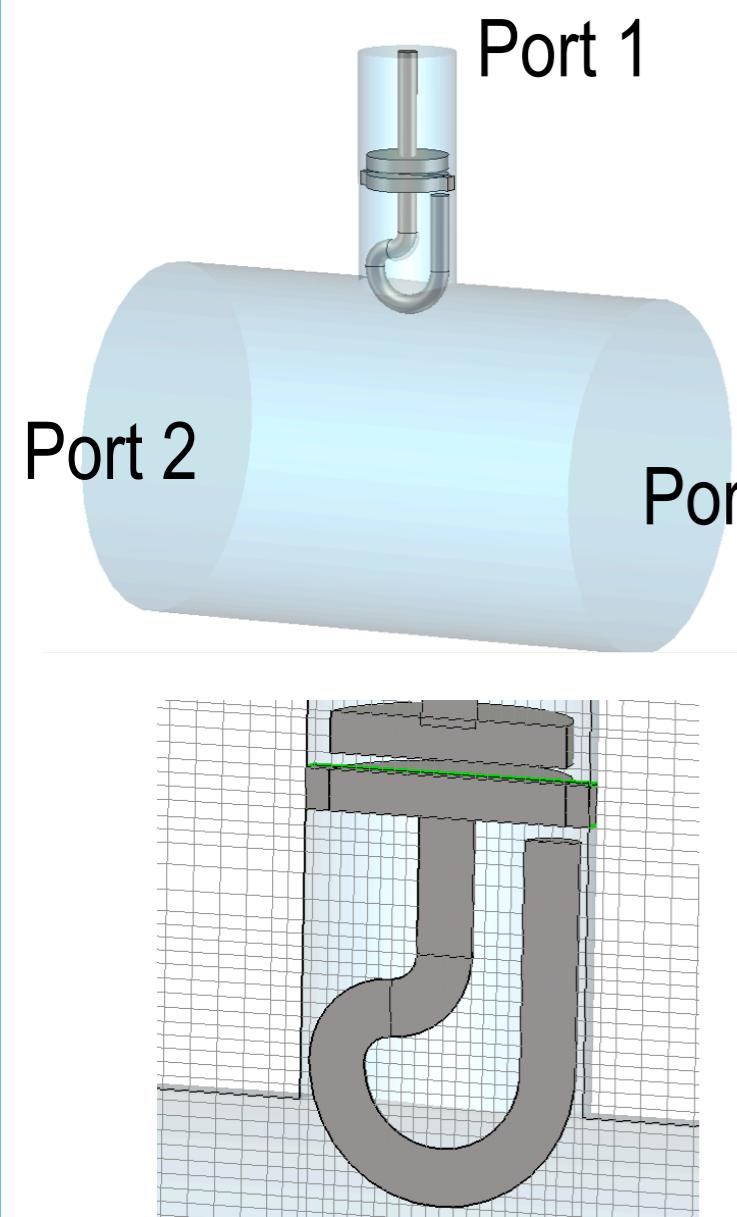


Filter Characteristics





First Simulation - CST MW Studio

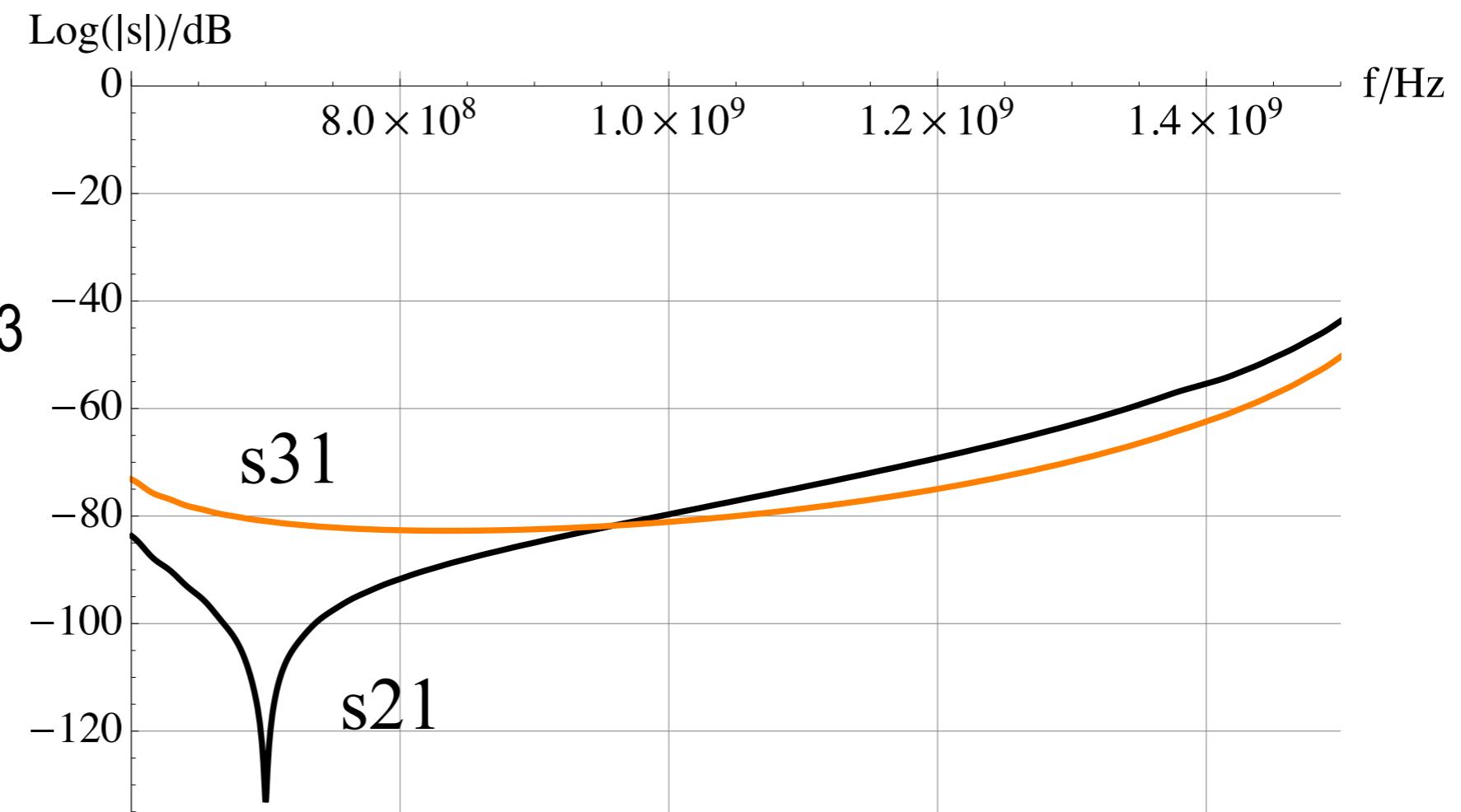
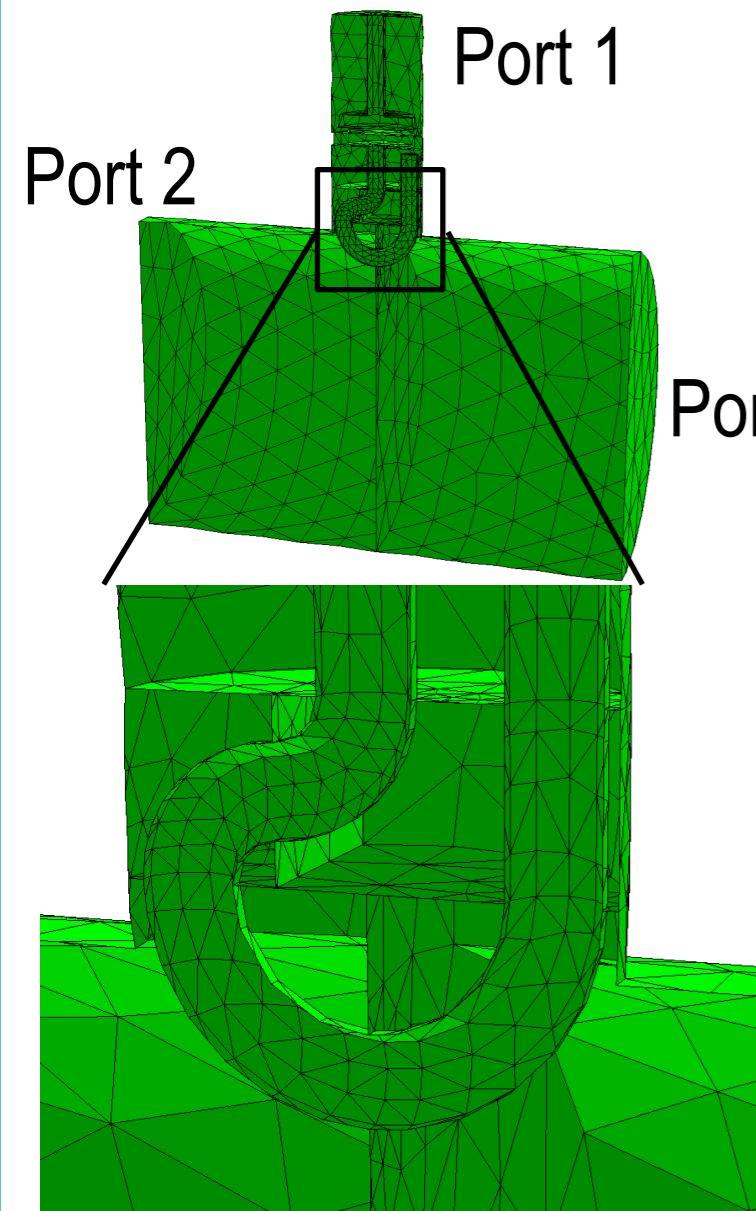


Transmission of TM01 to TEM, Computational Time ~ **1700s** on
4 Cores @ 3.2 GHz

HOM section discretized (528k meshcells total, first order)



Then - GPU Accelerated DG-FEM (NUDG*)



Transmission of TM01 to TEM, Computational Time ~400s on
GPU GTX 470

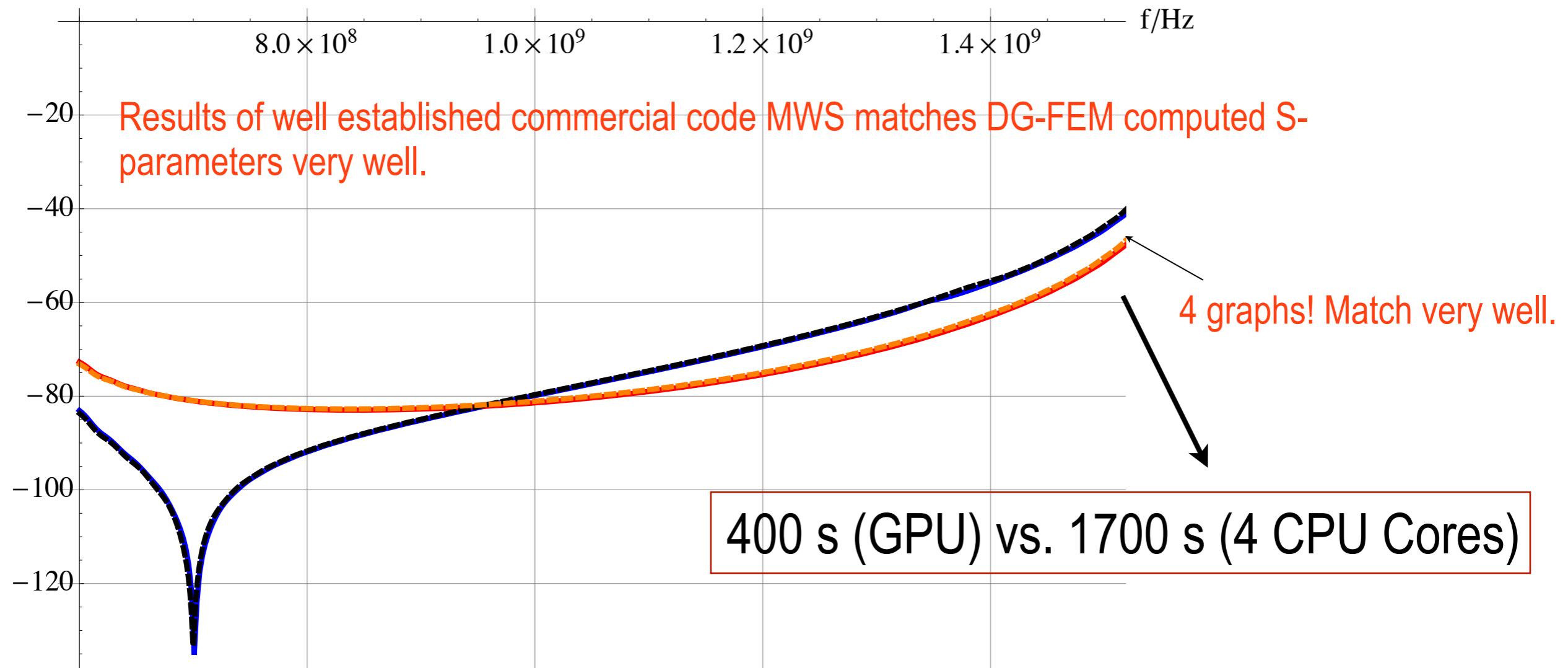
HOM section discretized (12k elements)

*www.nudg.org



Comparison of both schemes (accuracy vs. time)

$\text{Log}(|s|)/\text{dB}$



Transmission of TM01 to TEM, Comparison of computed transmissions

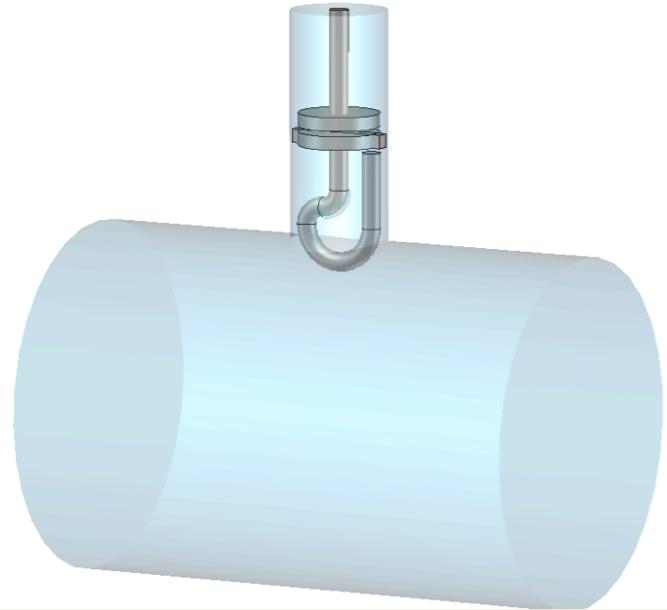
Speedup by a factor of ~ 4

=> use DG-FEM for further optimization!



Interlude - Further Speedup?

- MWS: Use more Cores?



1700 s (4 CPU Cores) => 1610 s (8 CPU Cores)
(Performance is limited by memory bandwidth, not arithmetic operations count!)

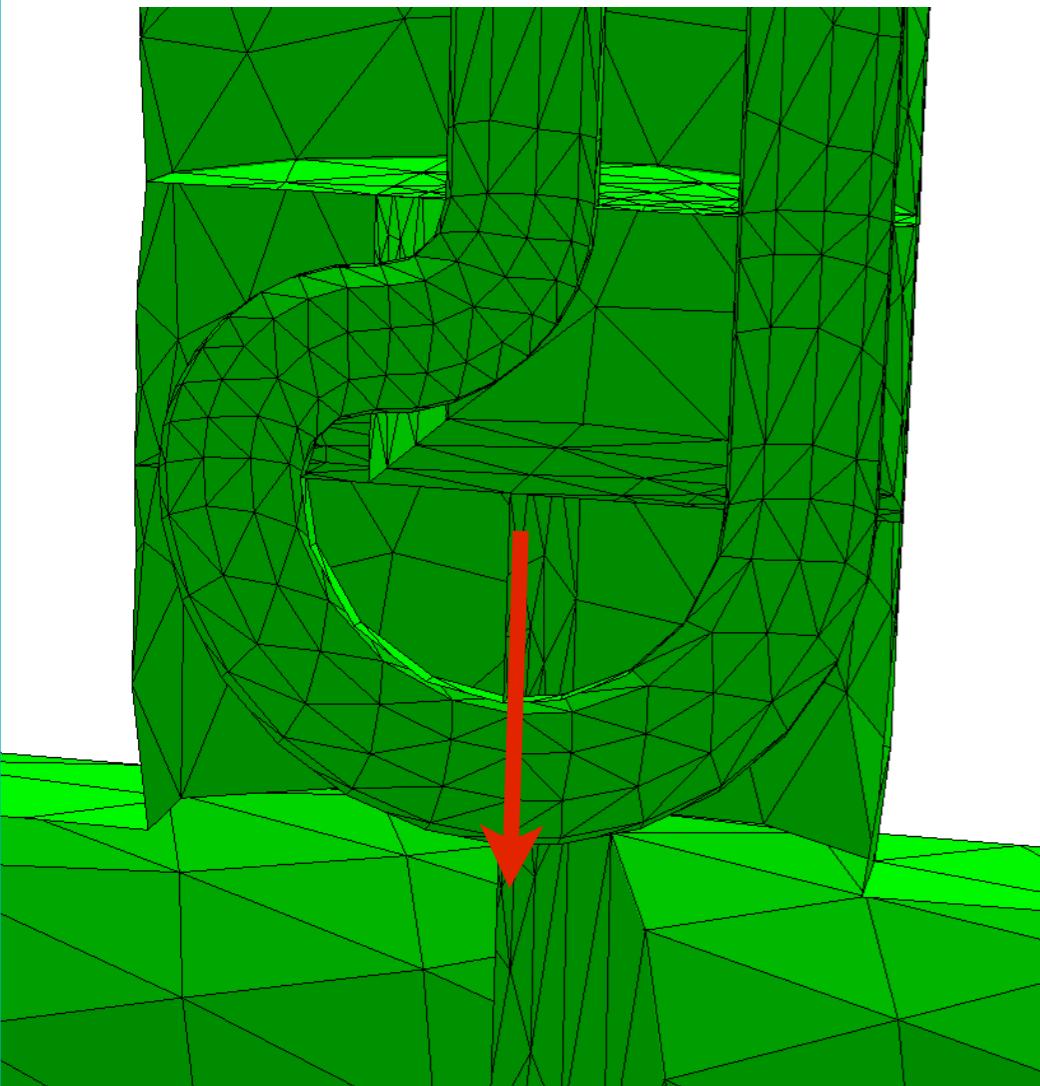
- DG - FEM:

- Local timestepping => Implementation in development (Expected gain ~ 2...3)
- Multiple GPUs => coming soon: GPU Cluster

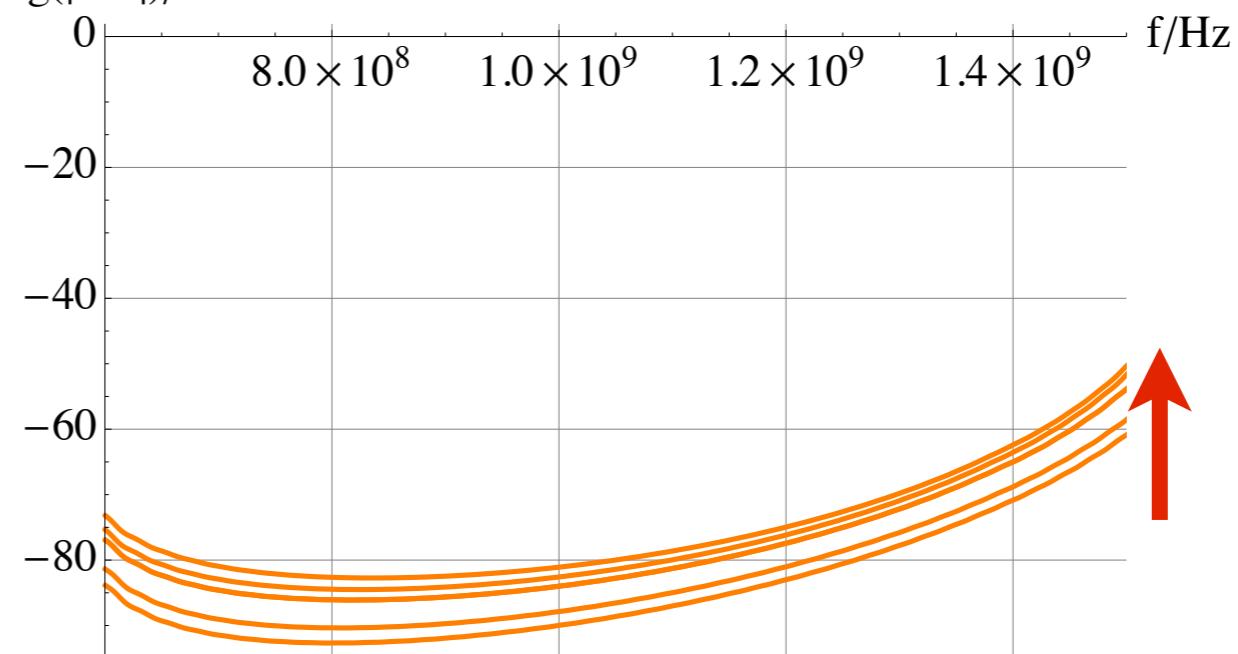
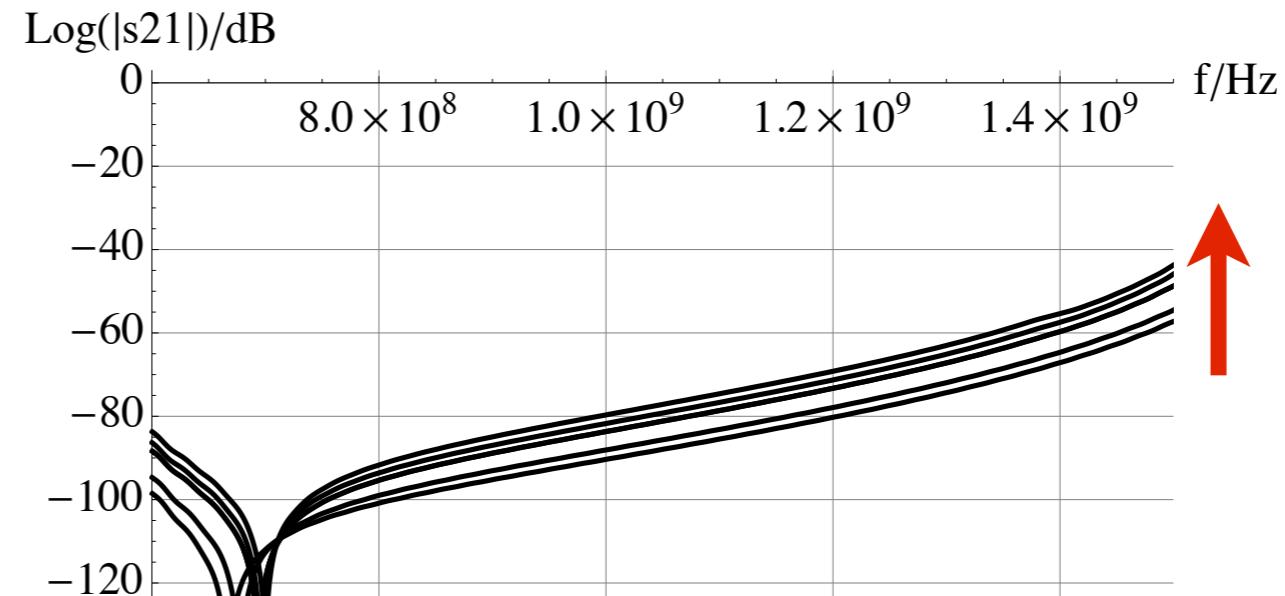
} Reduces optimization time
by at least one magnitude



Text example #1

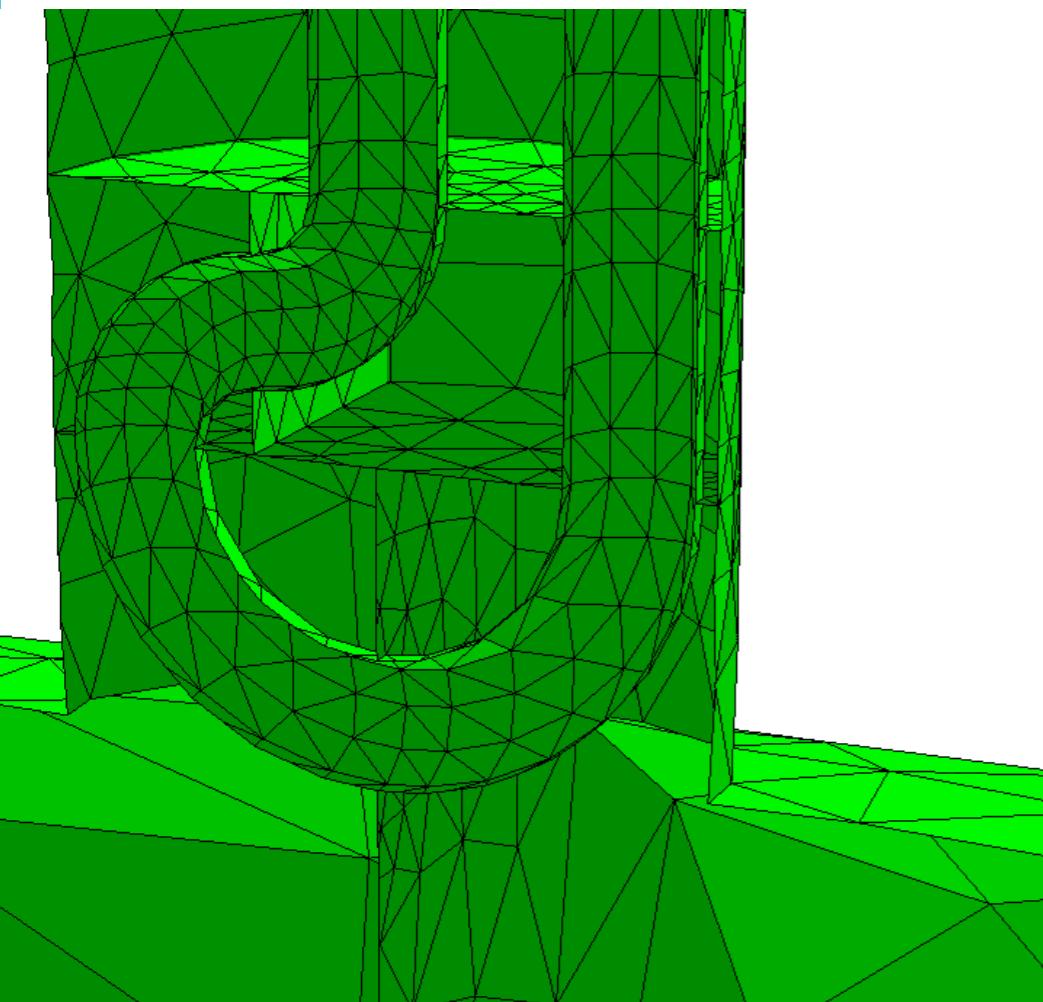


Lowering the „hook“ in the beam pipe

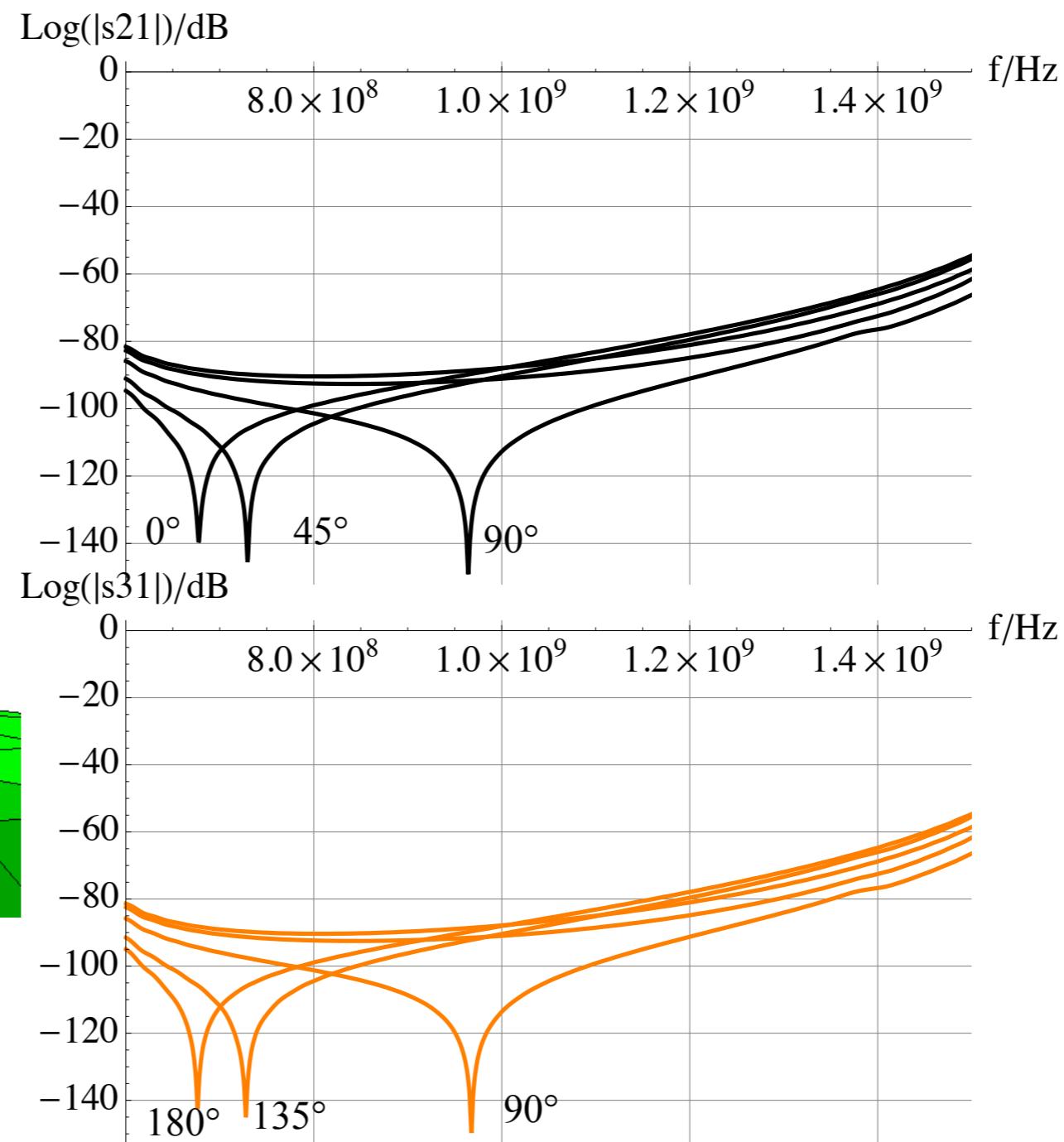




Text example #2

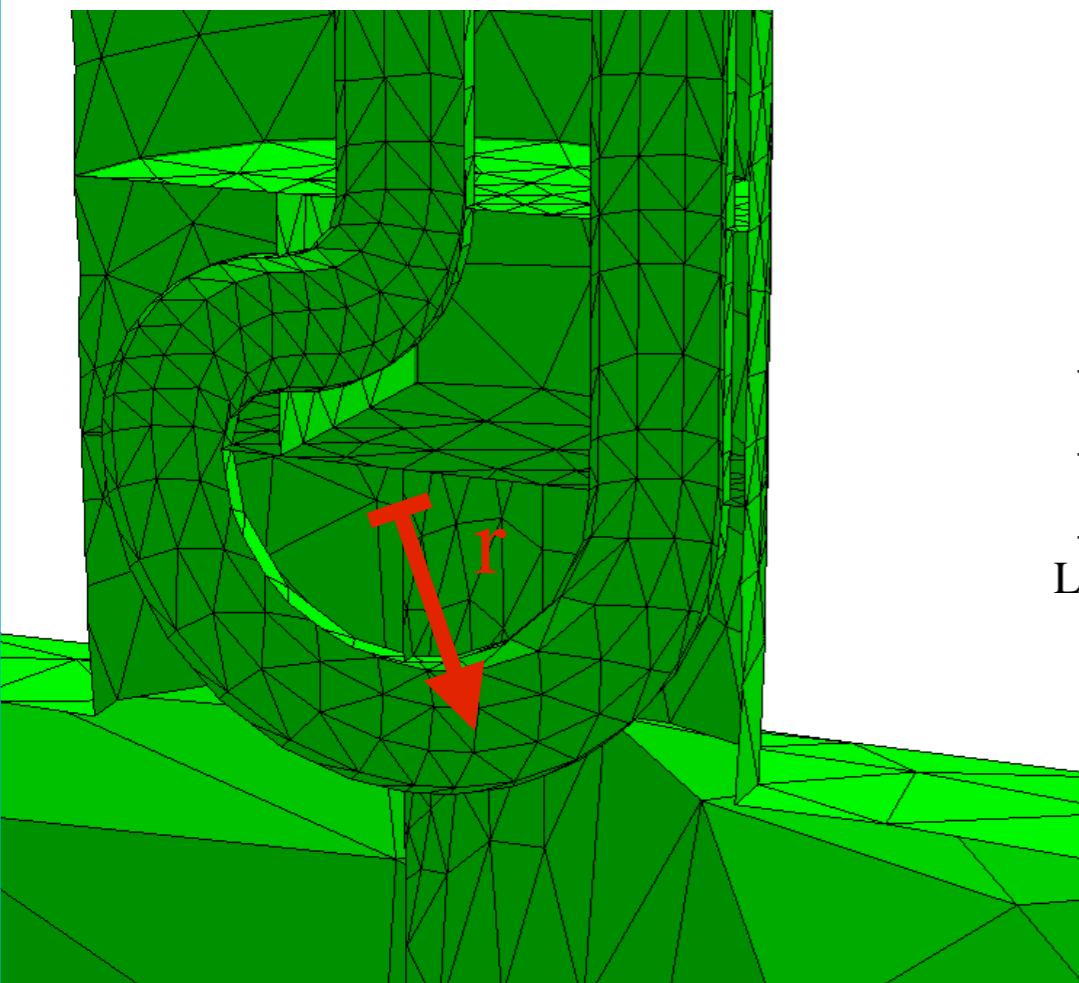


Rotation around axis

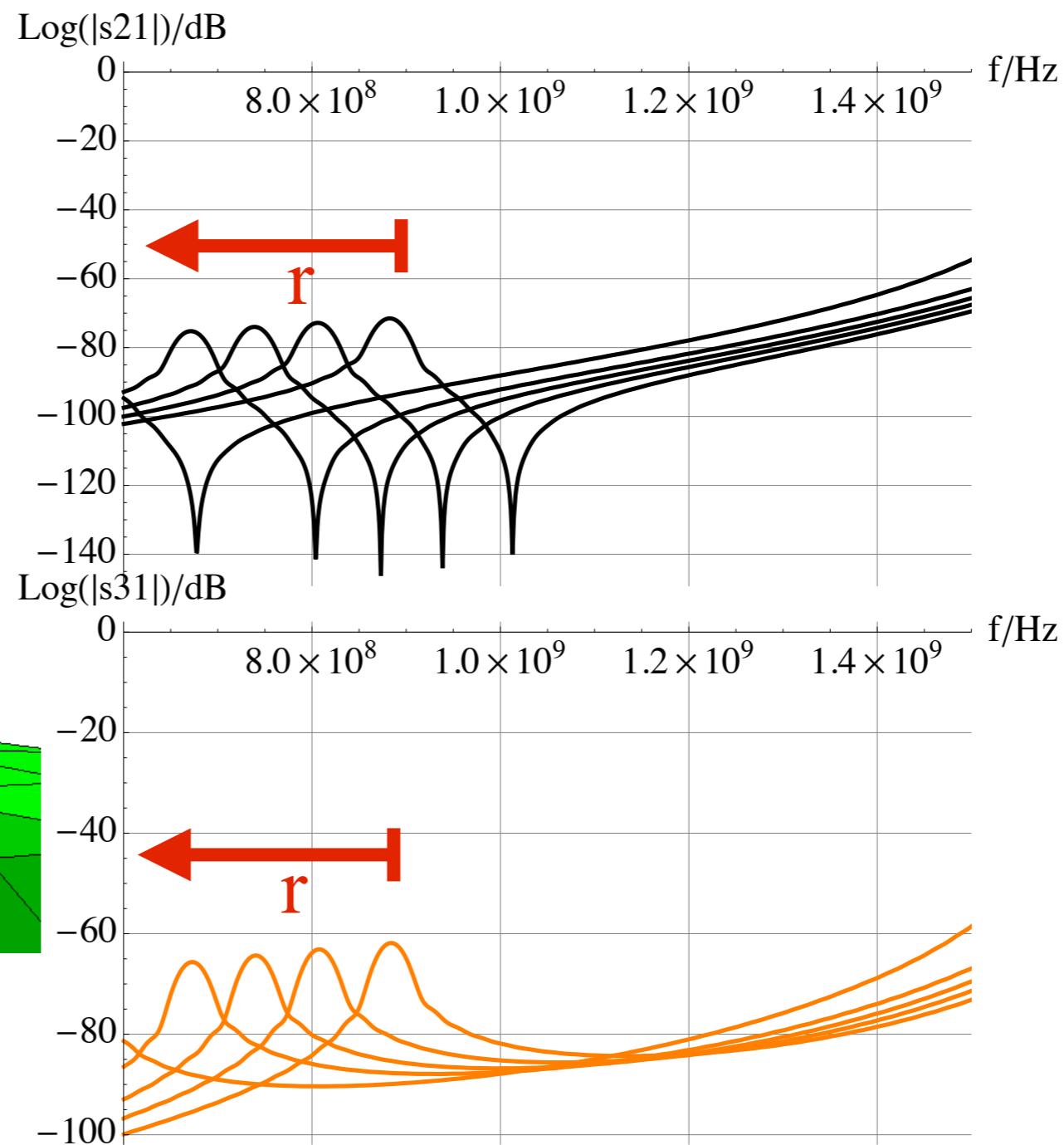




Text example #3



Scaling of the „hook’s“ radius





Conclusion

- Systematic optimization (= extensive parameter sweeps) is required for HOM coupler design
- Therefore, a suited numerical scheme is essential
- Based on an (preliminary) application geometry:
 - S-Parameters computed with DG-FEM are in very good agreement with well established code (MWS)
 - Computation time (and thus optimization time) can be reduced significantly by GPU accelerated DG-FEM